



# *Acyclic digraphs*

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### Definition

**An acyclic digraph** is a digraph in which there is no directed cycle.

### Definition

**A directed tree** is a weakly connected digraph in which is no quasi-cycle.

### Remark

If  $\vec{G} = (V, H)$  as an acyclic digraph then it can not contain both arcs  $(u, v)$  and  $(v, u)$  simultaneously, since, in this case, it would contain also following cycle  $(u, (u, v), v, (v, u), u)$ .

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$(u, (u, v), v, (u, v), u)$  is not a quasi-cycle, since it contains the same arc  $(u, v)$  twice.

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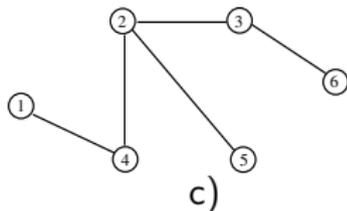
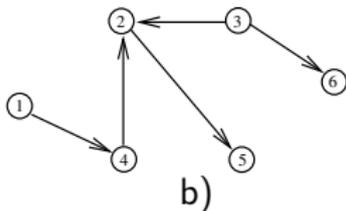
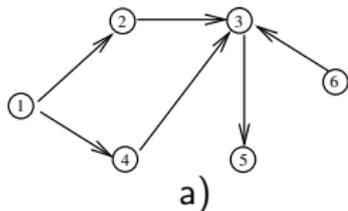
We can create for every acyclic digraph  $\vec{G} = (V, H)$  a (non directed) graph  $G' = (V, H')$  with the same vertex set  $V$  and with edge set  $H'$  defined as

$$H' = \{\{u, v\} \mid (u, v) \in H\} . \quad (1)$$

Edge set  $H'$  is the arc set  $H$  in which we „forget“ direction.

Since an acyclic digraph can contain at most one arc from  $(u, v)$ ,  $(v, u)$  for every pair of vertices  $u \in V$ ,  $v \in V$ , it holds

$$|H'| = |H|.$$



*Obr.:* a) Weakly connected acyclic digraph, which is not a directed tree.

b) Directed tree  $\vec{G}$ .

c) Non directed tree corresponding to  $\vec{G}$ .

### Theorem

Following assertions are equivalent:

- a) Digraph  $\vec{G} = (V, H)$  je a directed tree.
- b) There exists exactly one  $u$ - $v$  quasi-path in digraph  $\vec{G} = (V, H)$  for every  $u, v \in V$ .
- c) Digraph  $\vec{G} = (V, H)$  is weakly connected and every arc of arc set  $H$  is a bridge in  $\vec{G} = (V, H)$ .  
(A bridge in a digraph is such an arc, after removing it the number of components rises.)
- d) Digraph  $\vec{G} = (V, H)$  is weakly connected and  $|H| = |V| - 1$ .
- e) Digraph  $\vec{G} = (V, H)$  does not contain a quasi-cycle and it holds  $|H| = |V| - 1$ .

## Properties of acyclic digraphs

### Theorem

Let  $\vec{G} = (V, H)$  be an acyclic digraph.

Then  $V$  contains at least one vertex  $z$  such that  $\text{iddeg}(z) = 0$   
and at least one vertex  $u$  such that  $\text{odeg}(u) = 0$ .

PROOF.

Let

$$\mu(v_1, v_k) = (v_1, (v_1, v_2), v_2, \dots, (v_{k-1}, v_k), v_k)$$

be a directed path in digraph  $\vec{G}$  with maximum number of arcs.

We show that  $\text{odeg}(v_k) = 0$ .



If  $\text{odeg}(v_k) > 0$ ,

then there exists at least one arc (dashed) outgoing from  $v_k$ ,  
which extends path  $\mu(v_1, v_k)$  (contradiction with path having maximum number of arcs)  
or closes a cycle (contradiction with acyclicity of  $\vec{G}$ )

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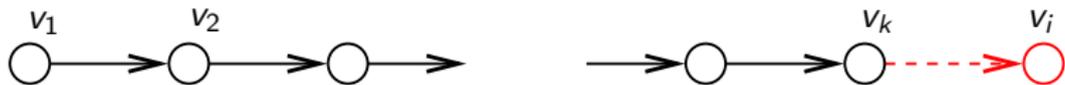
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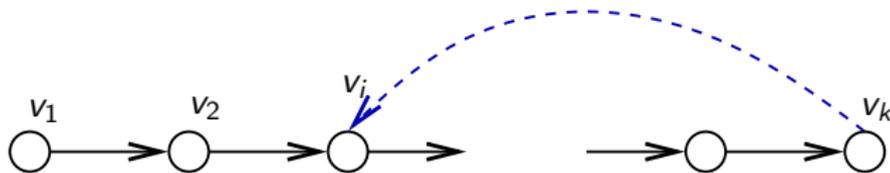
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A digraph  $\vec{G} = (V, H)$  is acyclic if and only if its vertex set  $V$  can be ordered into sequence

$$v_1, v_2, \dots, v_n \quad (2)$$

so that it holds:

$$\text{If } (v_i, v_k) \in H \text{ then } i < k. \quad (3)$$

### Definition

Numbering of vertices  $v_1, v_2, \dots, v_n$  of an acyclic digraph  $\vec{G} = (V, H)$  for which it holds:

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### Algorithm

**Algorithm 1.** for topological ordering of acyclic digraph  $\vec{G} = (V, H)$ .

- **Step 1.** Set  $i := 1$ .
- **Step 2.** {Digraph  $\vec{G} = (V, H)$  contains at least one vertex such that  $v \in V$ , že  $\text{ideg}(v) = 0$ .}  
Take such vertex  $v \in V$  for which  $\text{ideg}(v) = 0$  and set  $v_i := v$ .
- **Step 3.** If  $V - \{v\} = \emptyset$  STOP,  
otherwise  $\vec{G} := \vec{G} - \{v\}$ ,  $i := i + 1$  and Goto Step 2.



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### Algorithm

#### Algorithm II. for topological ordering of acyclic digraph

$\vec{G} = (V, H)$ .

- **Step 1.** Assign a label  $d(v) := \text{ideg}(v)$  for every vertex  $v \in V$ .  
Determine the subset  $V_0 \subseteq V$  of vertex set  $V$  containing all vertices with zero label  $d(\ )$ , i. e.

$$V_0 = \{v \mid v \in V, d(v) = 0\}.$$

Set  $k := |V_0|$  and order the elements of  $V_0$  into arbitrary sequence  $\mathcal{P} = v_1, v_2, \dots, v_k$ .

Set  $i := 1$ . Set  $r := i$ .

- **Step 2.** For all vertices  $w \in V^+(r)$  do:  
 $d(w) := d(w) - 1$ . If  $d(w) = 0$  then set  $k := k + 1$ ,  $v_k := w$ .
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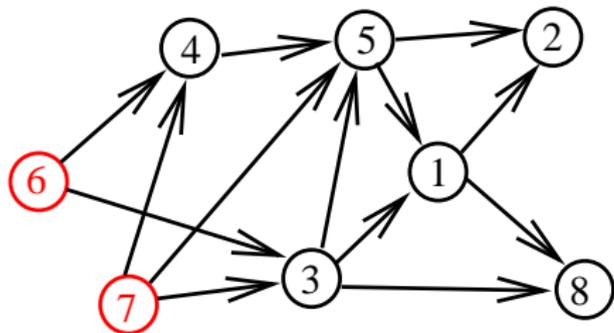
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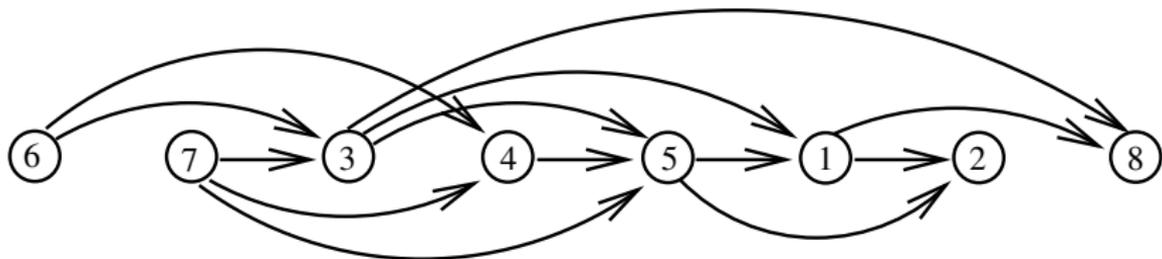
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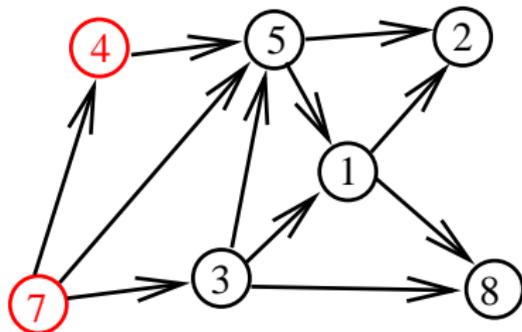
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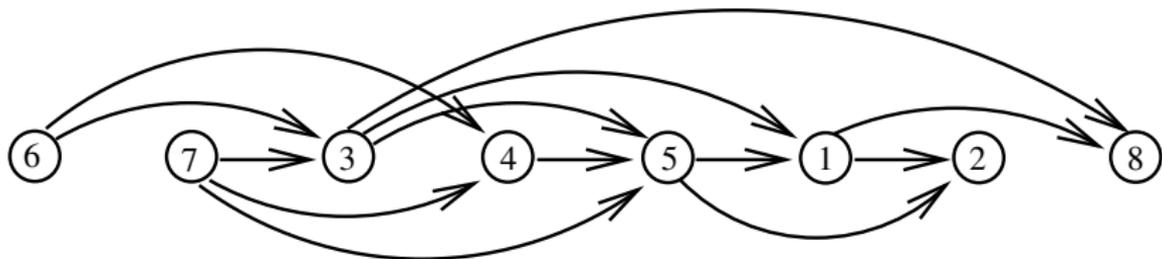
$i$	$v(i)$	1	2	3	4	5	6	7	8
		$d(v)$							
-	-	2	2	2	2	3	0	0	2
1	6	2	2	1	1			0	2
2	7	2	2	0	0	2			2
3	3	1	2			1			1
4	4	1	2			0			1
5	5	0	1						1
6	1		0						0
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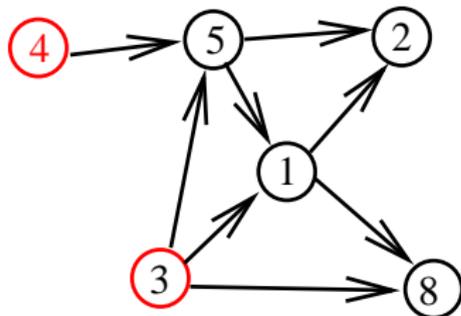
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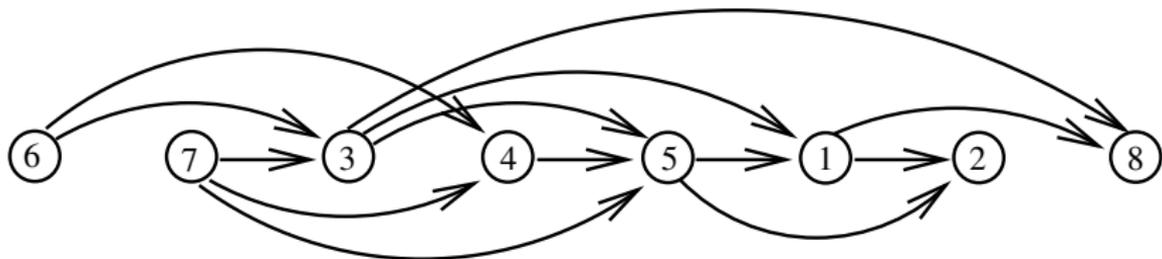
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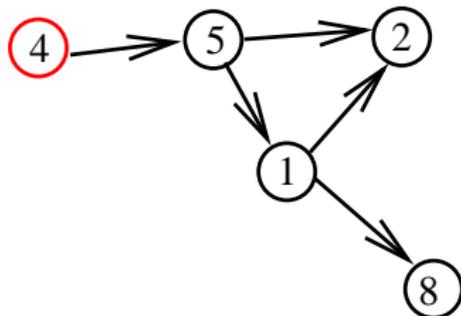
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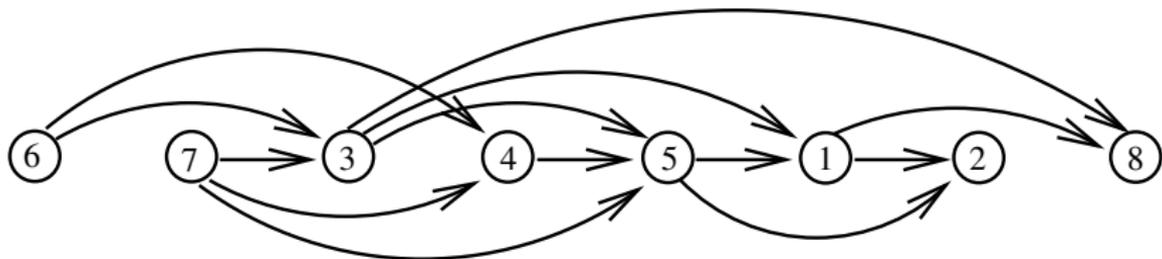
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2	7	2	2	<b>0</b>	<b>0</b>	<b>2</b>			2
3	3	<b>1</b>	2			<b>1</b>			<b>1</b>
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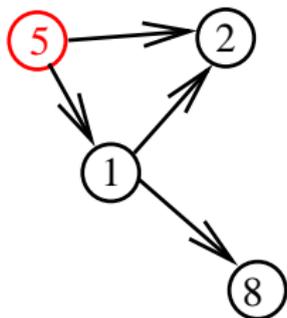
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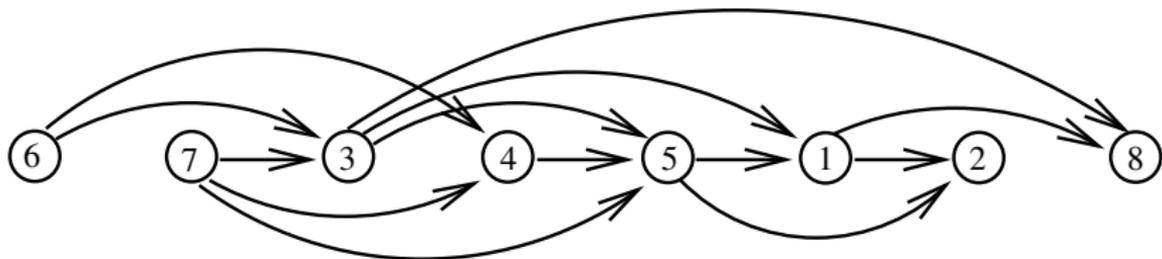
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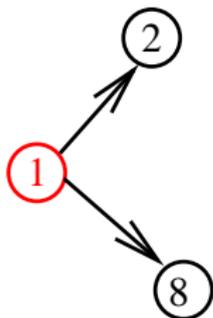
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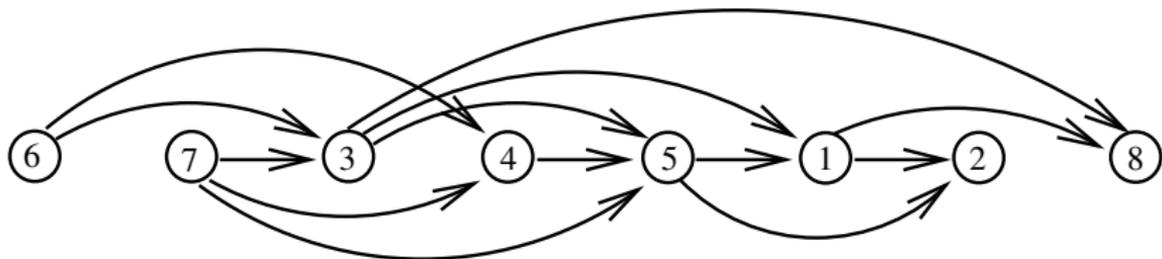
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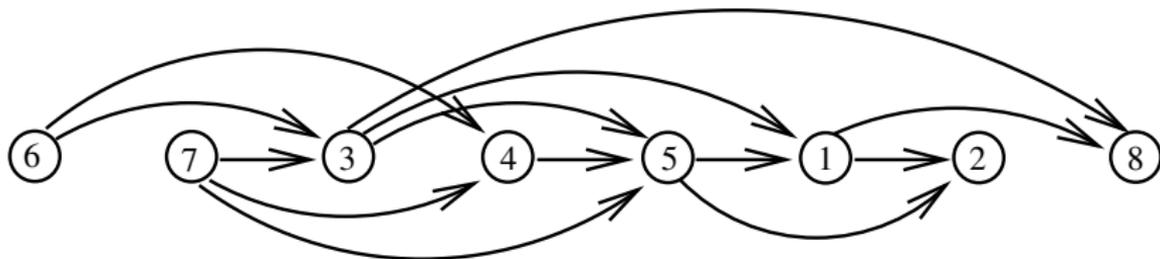


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5	5	<b>0</b>	<b>1</b>						1
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2

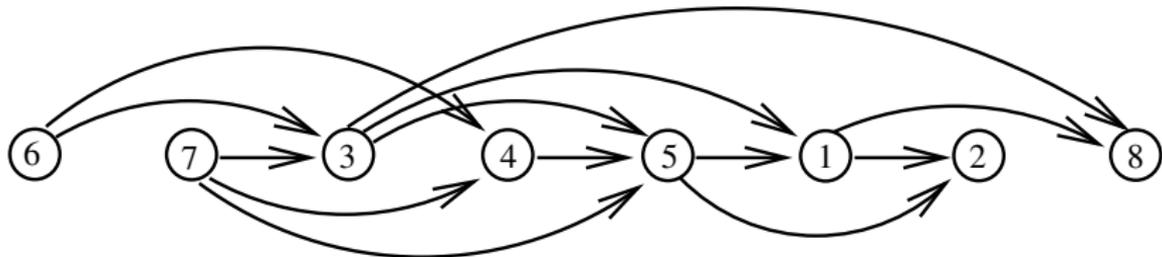
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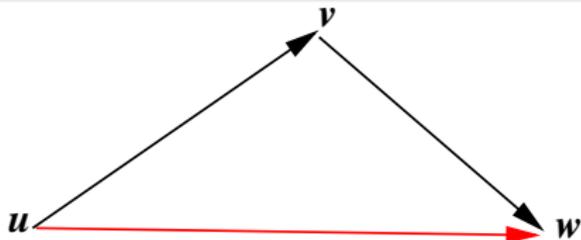
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8



### Definition

An acyclic digraph  $\vec{G} = (V, H)$  is **transitive**, if for every two arcs  $(u, v) \in H, (v, w) \in H$  there exists arc  $(u, w) \in H$ .



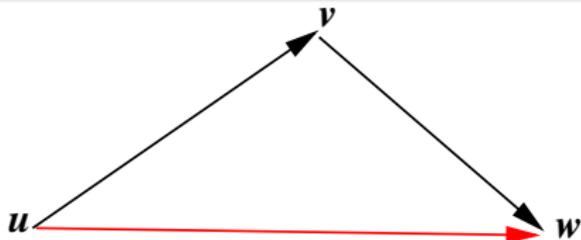
In a transitive digraph there is a direct arc  $(u, w)$  for every pair of arcs  $(u, v), (v, w)$

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### Definition

**A transitive closure**  $\vec{G}_T$  of a digraph  $\vec{G}$ , is minimal transitive digraph containing as a subgraph digraph  $\vec{G}$ .

**A transitive reduction**  $\vec{G}_R$  of a digraph  $\vec{G}$  is minimal spanning subgraph of digraph  $\vec{G}$  with the same reachability of vertices as in digraph  $\vec{G}$ .

- a) Digraph  $\vec{G}$ . b) Transitive closure  $\vec{G}_T$  of digraph  $\vec{G}$ .  
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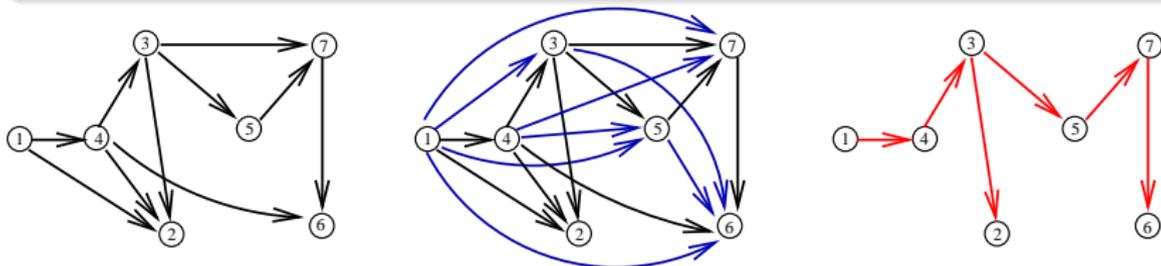
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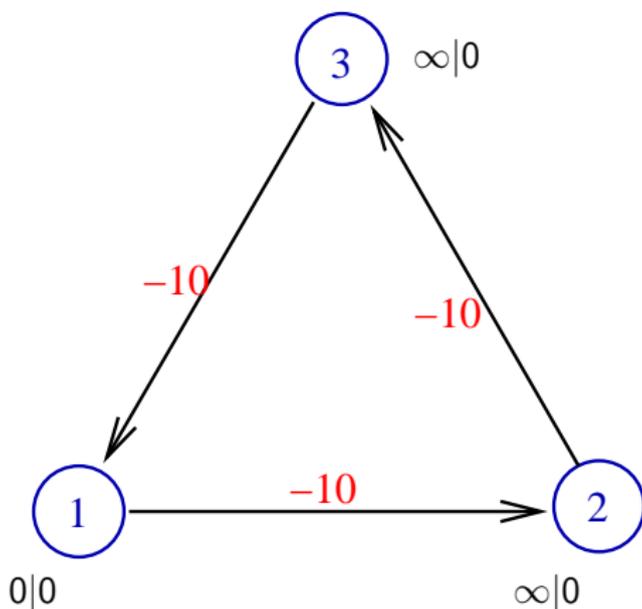
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## Shortest path problem in the general case of arc weights

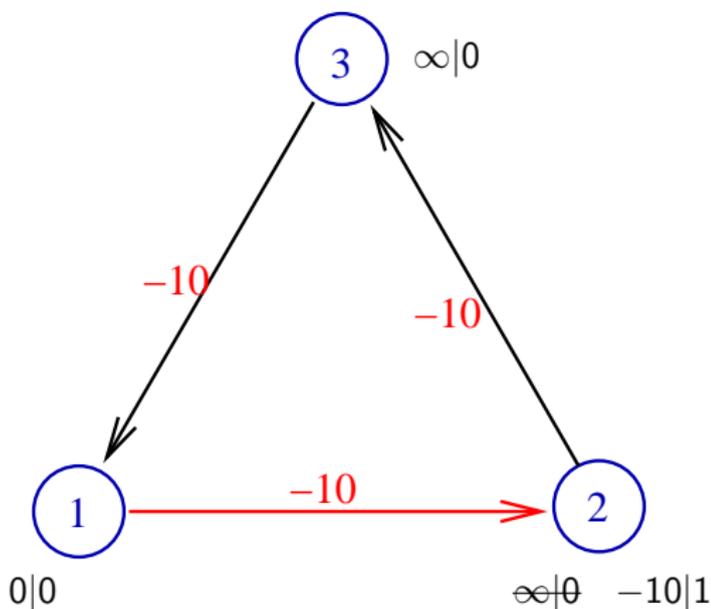
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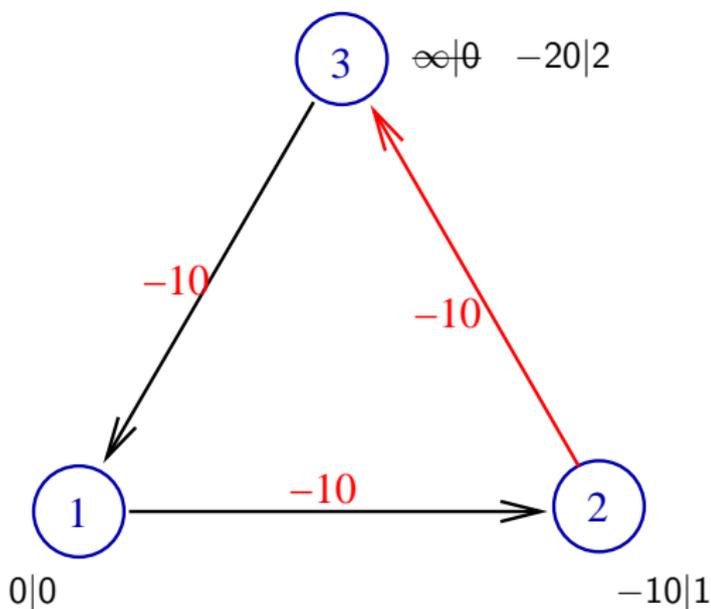
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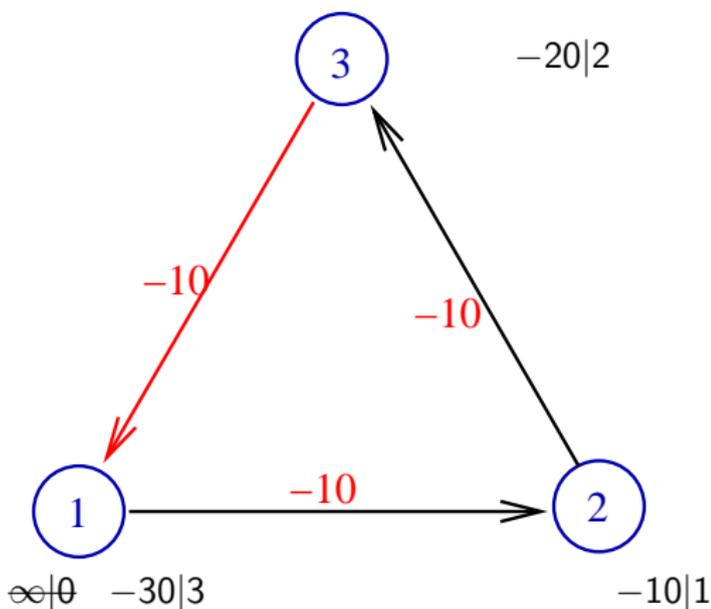
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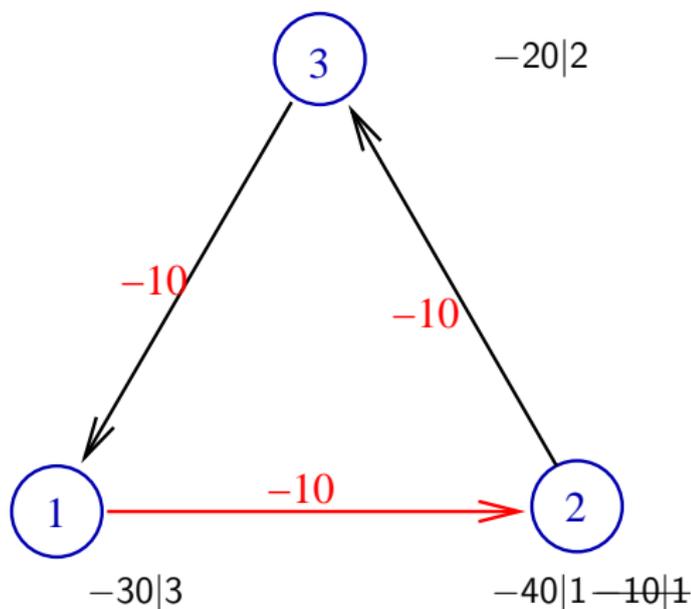
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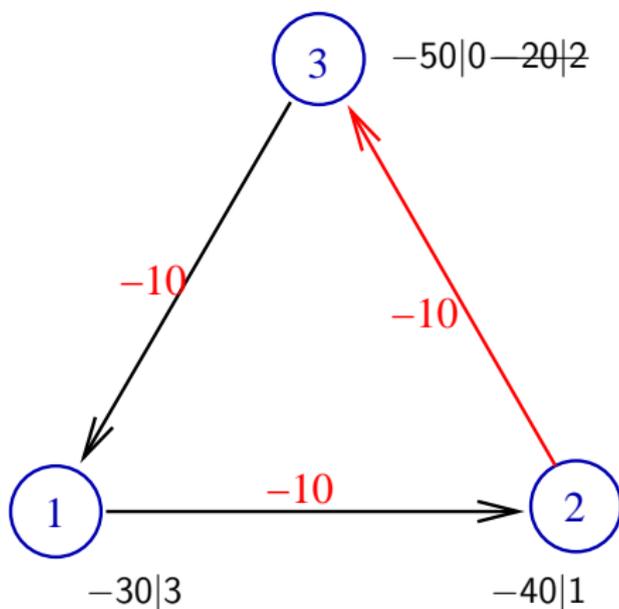
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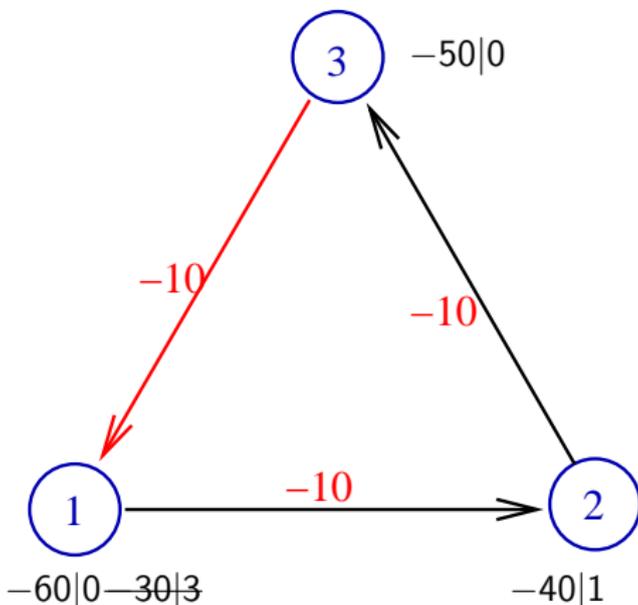
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**Shortest path algorithm for an acyclic digraph.** This algorithm will find all shortest  $u$ - $v$  directed paths from a fixed vertex  $u \in V$  into all reachable vertices  $v \in V$  in an edge weighted digraph  $\vec{G} = (V, H, c)$  with general edge weight  $c(h)$ .

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### Definition

Let  $\vec{G} = (V, H, c)$  be an arc weighted digraph, let  $u \in V, v \in V$ .

**Longest directed  $u-v$  path** in digraph  $\vec{G} = (V, H, c)$  is that directed  $u-v$  path which has largest length of all directed  $u-v$  paths.

### Remark

Longest path in an edge weighted graph  $G = (V, H, c)$  can be defined by the same way.

### Remark

- Shortest path problem in an arc weighted digraph  $\vec{G} = (V, H, c)$  with nonnegative arc weights (in which  $c(h) \geq 0 \forall h \in H$ ) is polynomially solvable.
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  - An activity is an elementary amount of work which is from our point of view indivisible.
  - Every activity is determined by its fixed processing time which can be different from activity to activity. Activities can differ by processing time.
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We will say that activity  $A$  **precedes** activity  $B$  and write  $A \prec B$ , if activity  $B$  can start only after activity  $A$  ends.

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Precedence relation  $\prec$  je **transitive**, e. g. it holds:

If  $A \prec B$ ,  $B \prec C$ , then  $A \prec C$ .

If activity  $B$  has to wait for the end of activity  $A$  and activity  $C$  has to wait for the end of activity  $B$ , then activity  $C$  can not start sooner than activity  $A$  ends.

Precedence relation  $\prec$  is **antireflexive**, i. e.:

For no  $A \in \mathcal{E}$  it holds  $A \prec A$ ,

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Colorary: There does no exist a sequence of activities  $A_1, A_2, \dots, A_n$  such that

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**Project planning problem**  $\mathcal{U}$  is given by the set of activities  $\mathcal{A}$ , precedence relation  $\prec$  on the set  $\mathcal{A}$  and by real function  $p : \mathcal{A} \rightarrow \mathbb{R}$  assigning to every activity  $A \in \mathcal{A}$  its processing time  $p(A)$ .  
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## Digraph of precedence

### Definition

A **digraph of precedence**  $\prec$  or a **precedence digraph** for corresponding project planning problem  $\mathcal{U}$  is a vertex weighted digraph

$$\vec{G}_{\prec} = (V, H_{\prec}, p),$$

whose vertex set is the set of all activities, i.e.  $V = \mathcal{A}$ , vertex weight  $p(v) > 0$  represents processing time of vertex – activity  $v \in V$  and arc set of  $\vec{G}_{\prec}$  is

$$H_{\prec} = \{(A, B) \mid A, B \in V, A \prec B\}.$$

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A **digraph of immediate precedence**  $\llcorner$  for project planning problem  $\mathcal{U}$  is a vertex weighted digraph

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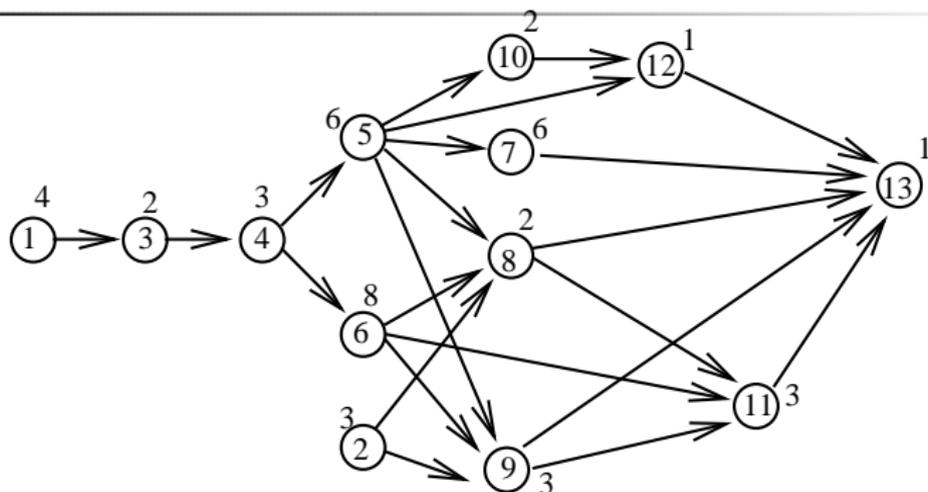


## Technological table of project

Technological table of project

Activity	No	Processing time	Succesor activities
Foundation excavations	1	4	3
Engineer networks	2	3	8 9
Concrete forming of foundations	3	2	4
Concreting of foundations	4	3	5 6
Outer walls	5	6	7 8 9 10 12
Inner partition walls	6	8	9 11
Roof	7	6	13
Electric instalations	8	2	11 13
Wate instalations	9	3	11 13
External rendering	10	2	12
Inner rendering	11	3	13
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## Precedence digraph corresponding to technological table



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## Schedule

To create a **schedule** for given project planning problem  $\mathcal{U}$  means to assign a time interval  $(b_A, c_A)$ ,  $b_A < c_A$  for every activity  $A$  in which activity  $A$  will be processed.

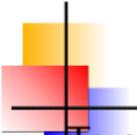
- $b_A$  – beginning time of activity  $A$
- $c_A$  – completion time of activity  $A$

A **feasible schedule** of project  $\mathcal{U}$  is a schedule for project  $\mathcal{U}$ , where it holds for arbitrary two activities  $A, B$ :

1.  $c_A - b_A = p(A)$
2. if  $A \prec B$ , then  $b_A < c_A \leq b_B < c_B$

### Remark

*Remember that it suffices (based on property 1. of feasible schedule) to determine for every activity  $A$  only its beginning  $b_A$ . Completion time can be then calculated as  $c_A = b_A + p(A)$ .*



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## Minimum completion time $T$

---

- There is a lot of feasible schedules for given project. However, we are interested in a feasible schedule which is optimal from certain point of view.
- We take very often  $C_{\max}$  – completion time of last activity as objective function.

$$C_{\max} = \max\{c_A \mid A \in \mathcal{A}\},$$

whereas we assume that project starts in time 0.

Value  $C_{\max}$  is called **makespan**.

- The goal of our project planning problem is to determine a feasible schedule for the given project  $\mathcal{U}$  with minimal makespan  $C_{\max}$ .
- Denote by  $T$  minimum of all completion times of all feasible schedules.

- Set start of project to the time 0.
- **Earliest possible start**  $z(A)$  of activity  $A$  is the least time moment measured from the beginning of project in which it is possible to start execute activity  $A$  whereby precedence relation  $\prec$  is kept.
- If earliest possible start is determined for all  $A \in \mathcal{A}$  then the minimum completion time  $T$  of project can be determined as:

$$T = \max\{z(A) + p(A) \mid A \in \mathcal{E}\}$$

- Suppose that the minimum completion time  $T$  of project is determined.

**Latest necessary completion time**  $k(A)$  of activity  $A$  is defined as the largest time moment measured from the beginning of project to which end of execution of activity  $A$  can be delayed without increase of the minimum completion time  $T$ .

- **Time reserve**  $R(A)$  of activity  $A$  is:

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### Remark

*It can be shown that*

- *A critical path in  $\vec{G}_{\leftarrow}$  contains only critical activities.*
- *The sum of vertex weights of arbitrary critical path in  $\vec{G}_{\leftarrow}$  is equal to the minimum completion time  $T$  of project.*

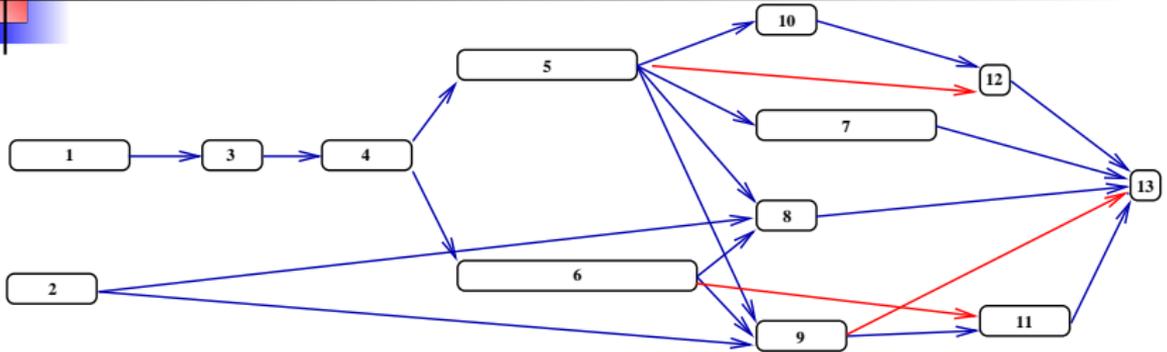
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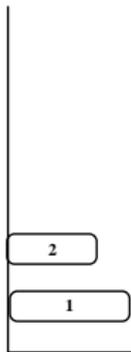
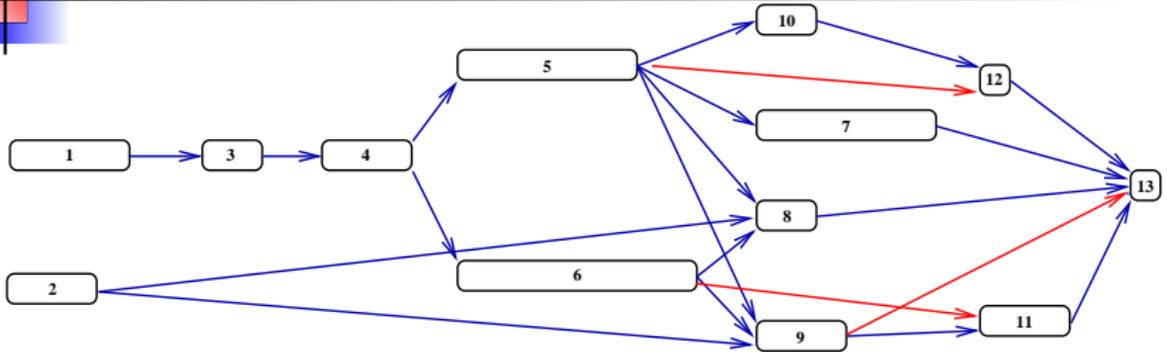
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## Determining earliest possible starts of activities



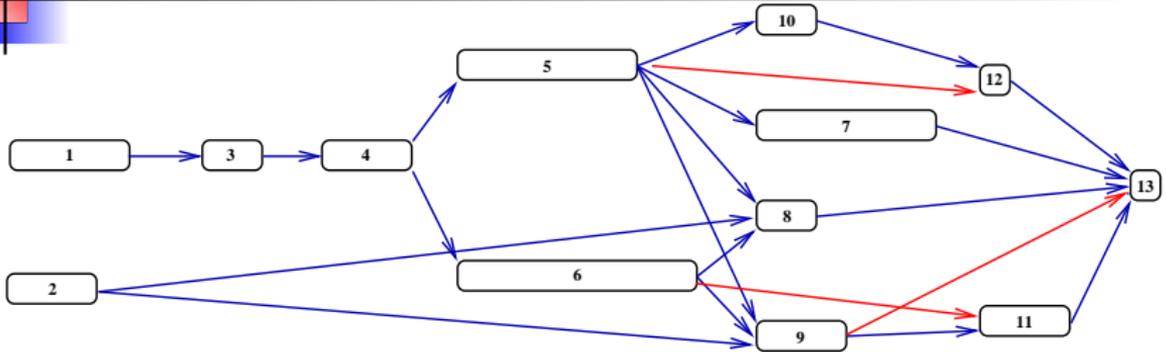
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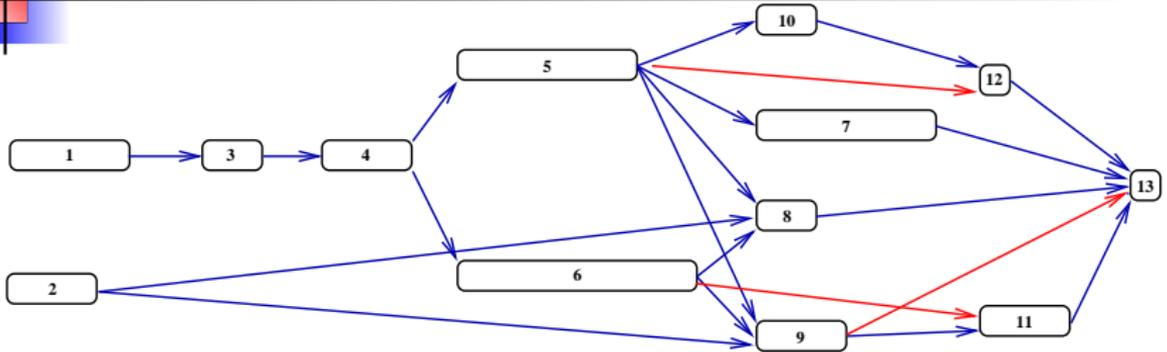
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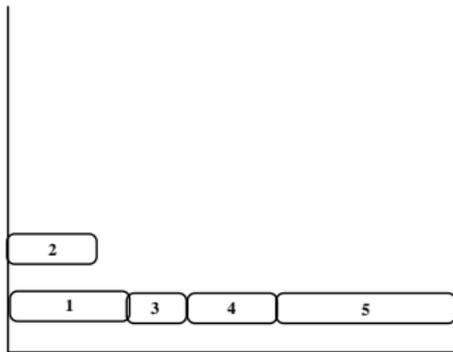
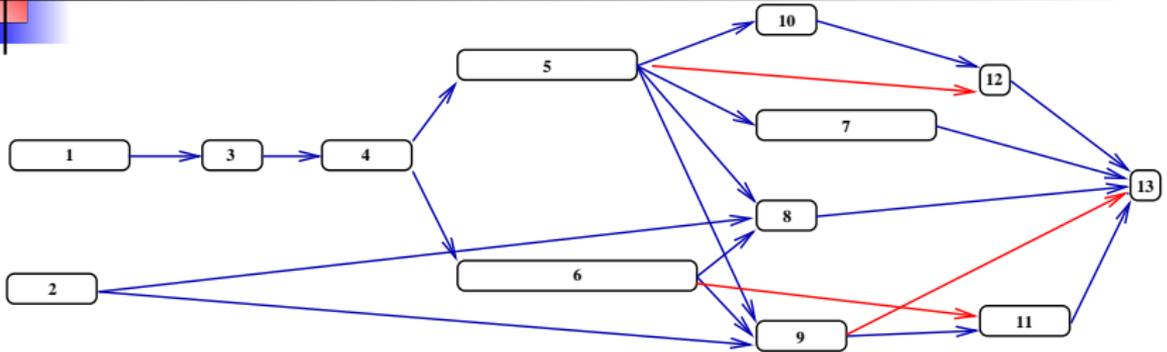
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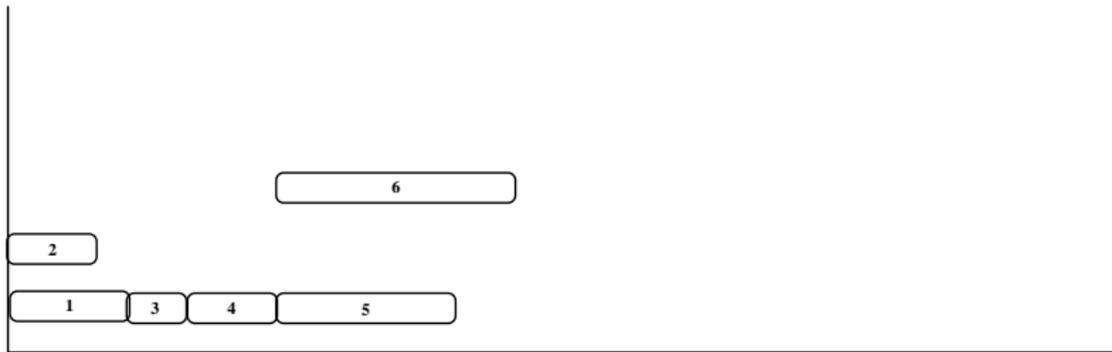
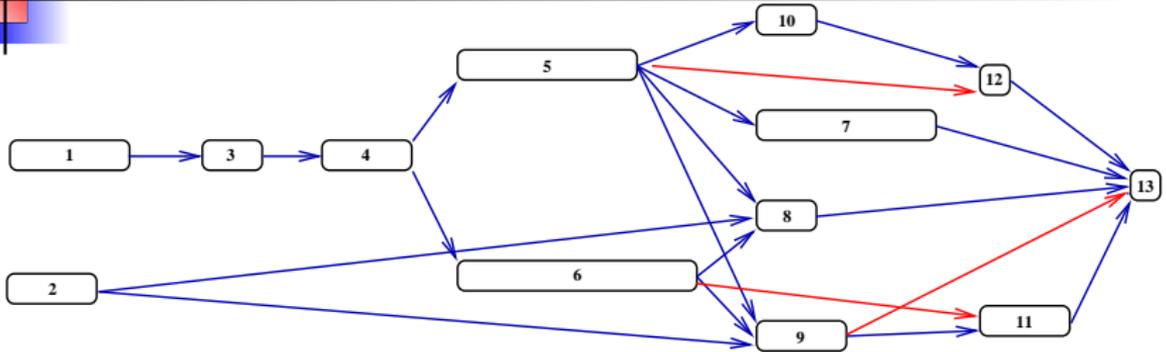
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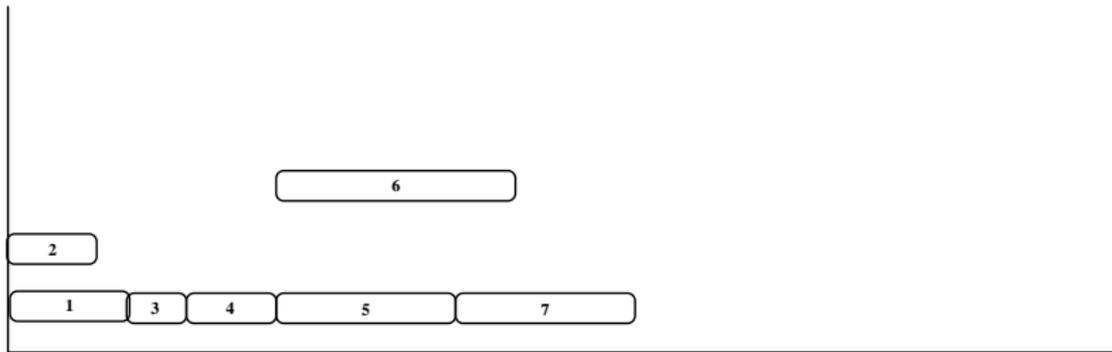
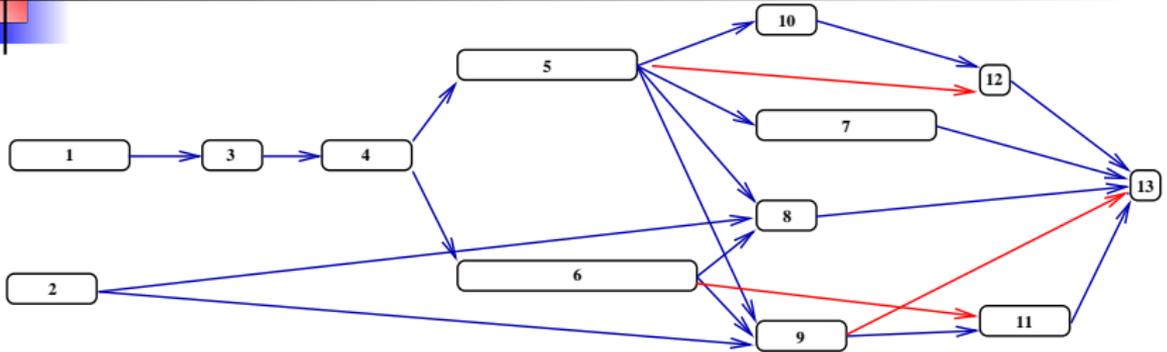
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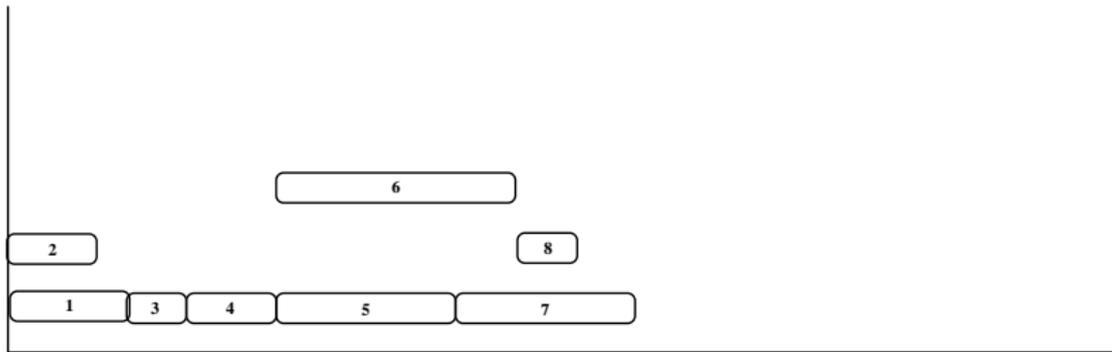
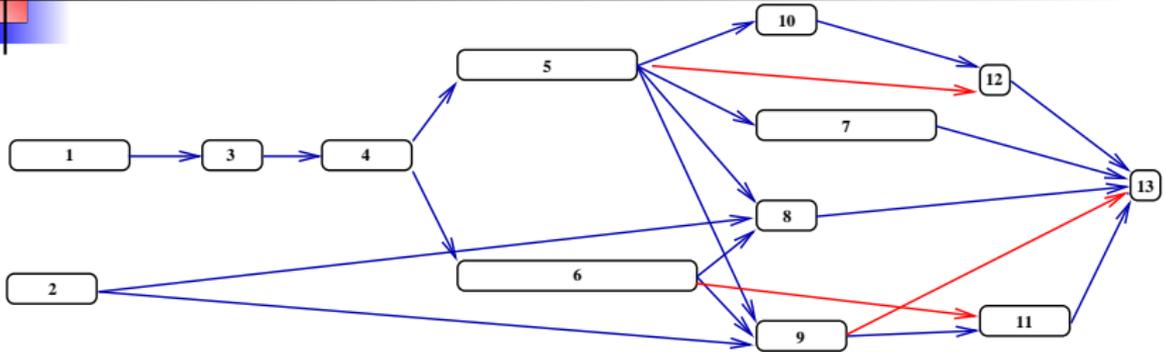
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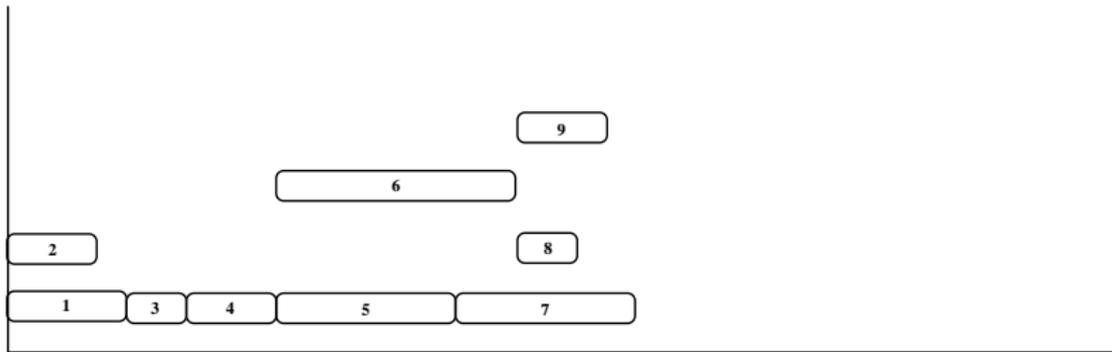
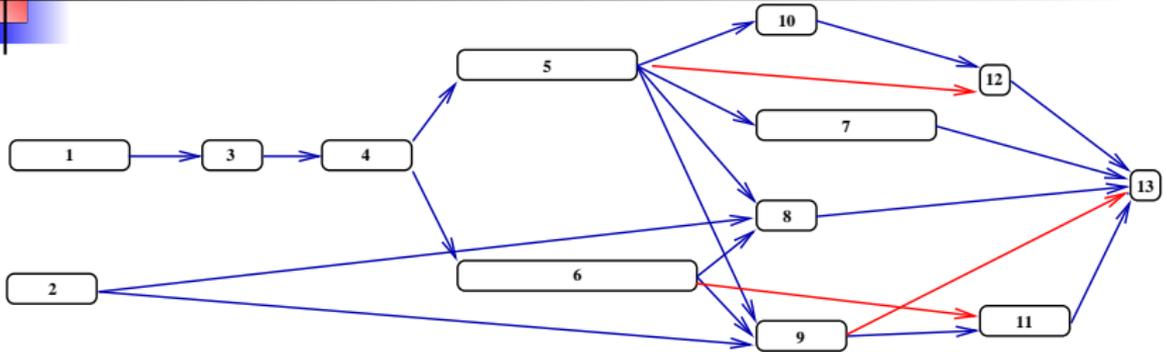
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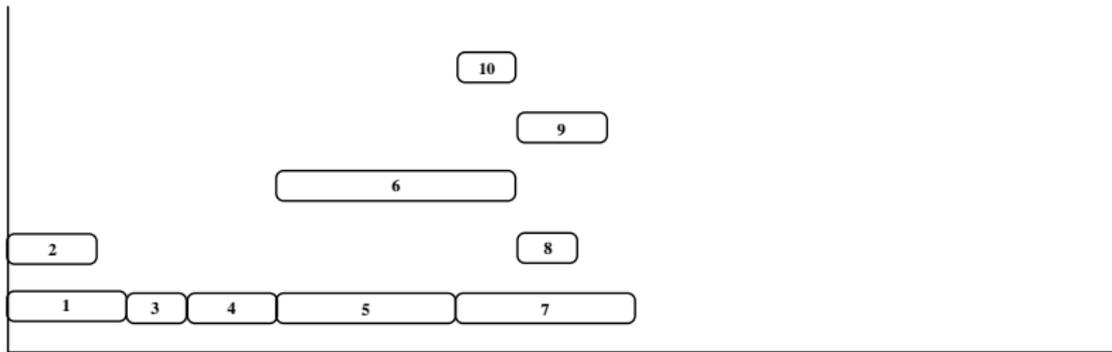
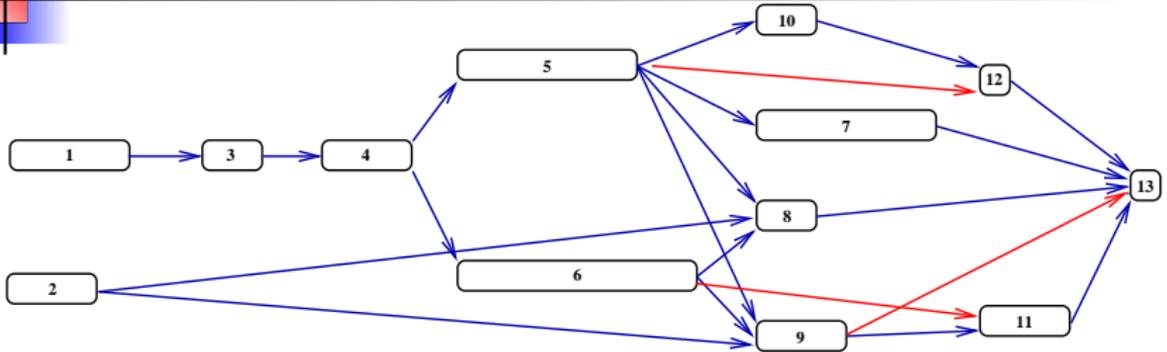
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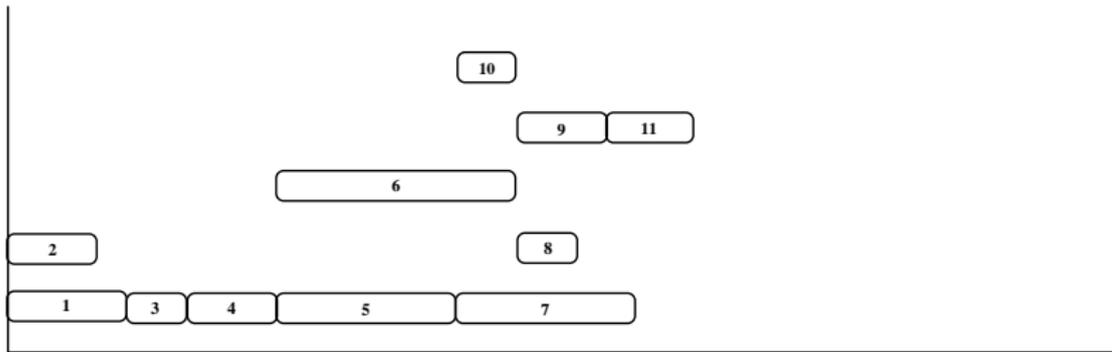
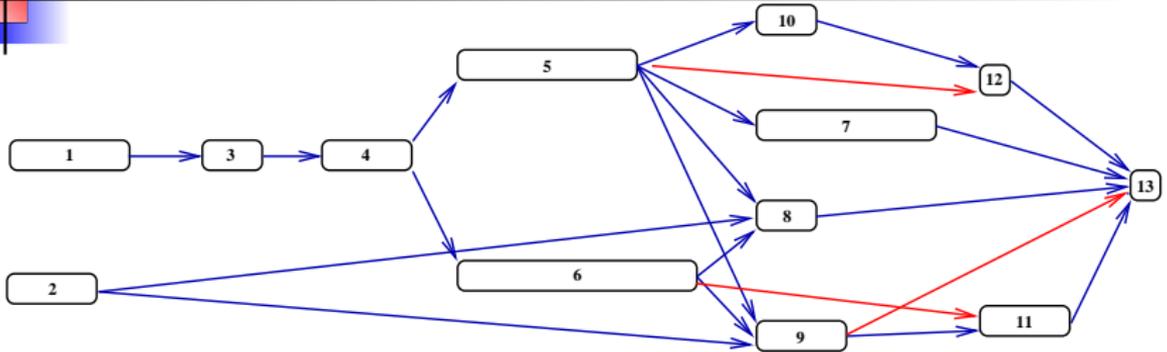
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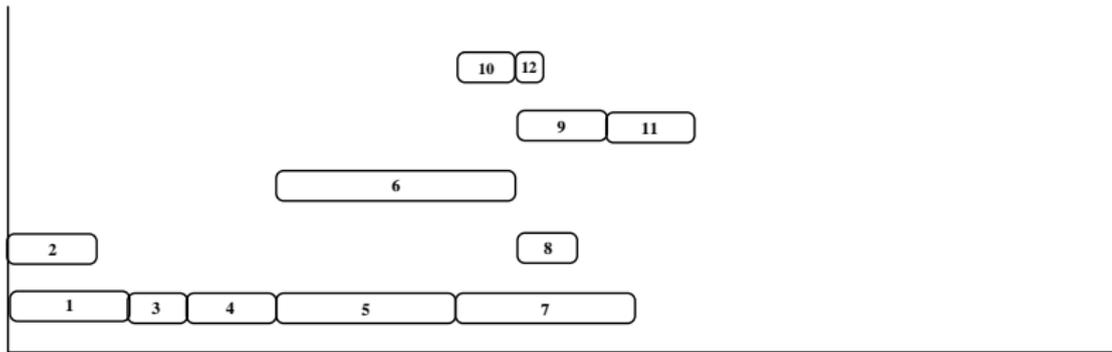
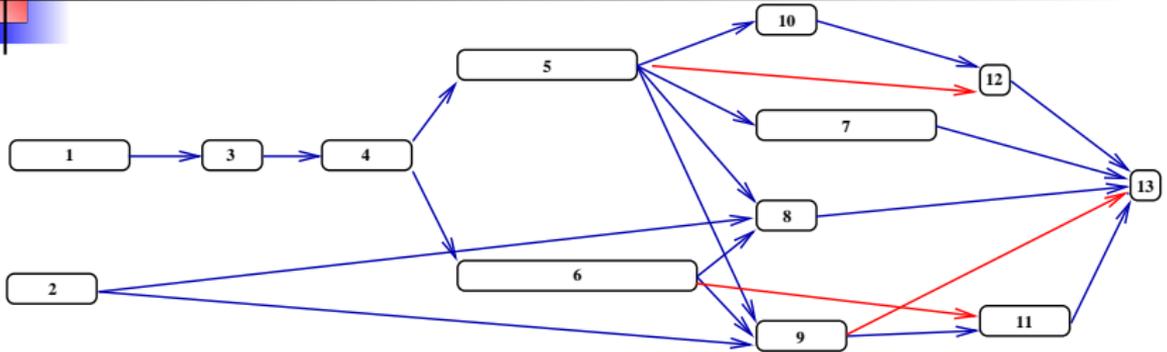
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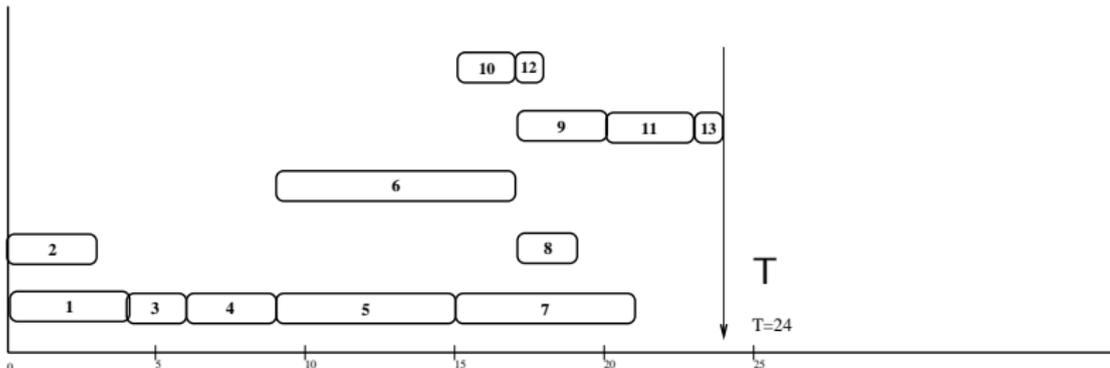
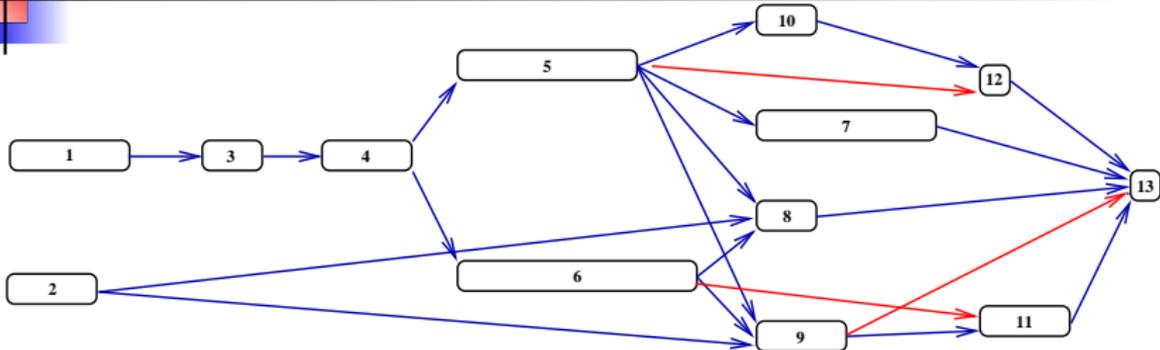
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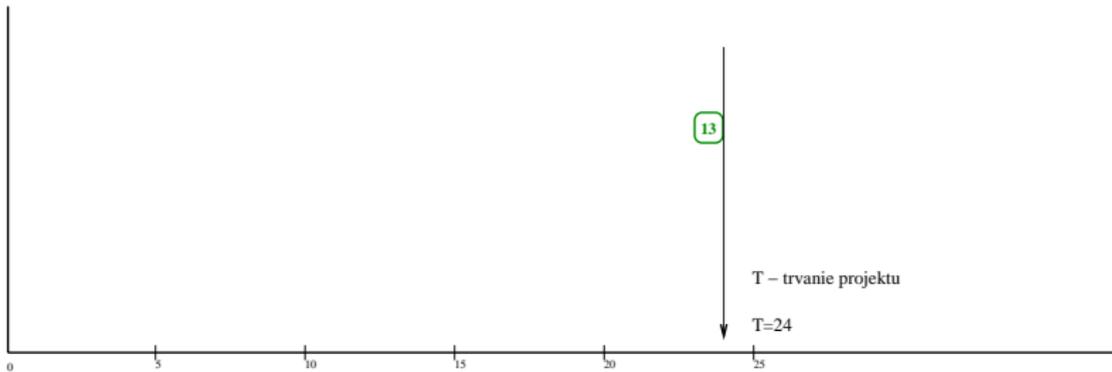
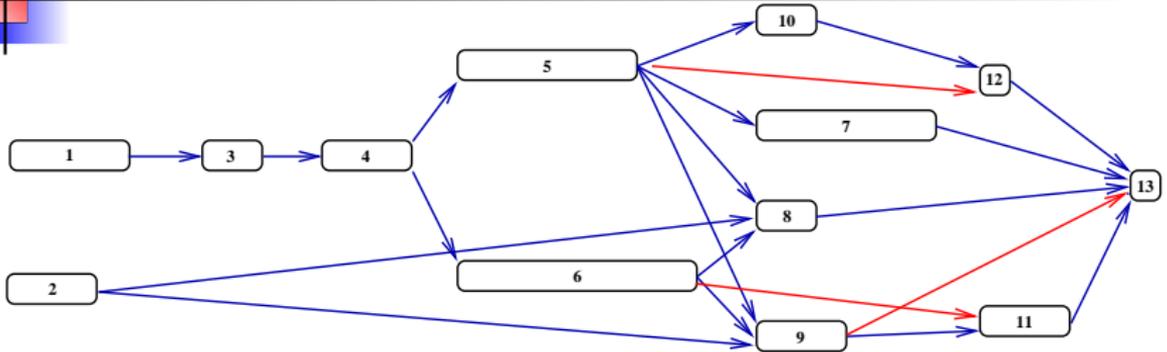
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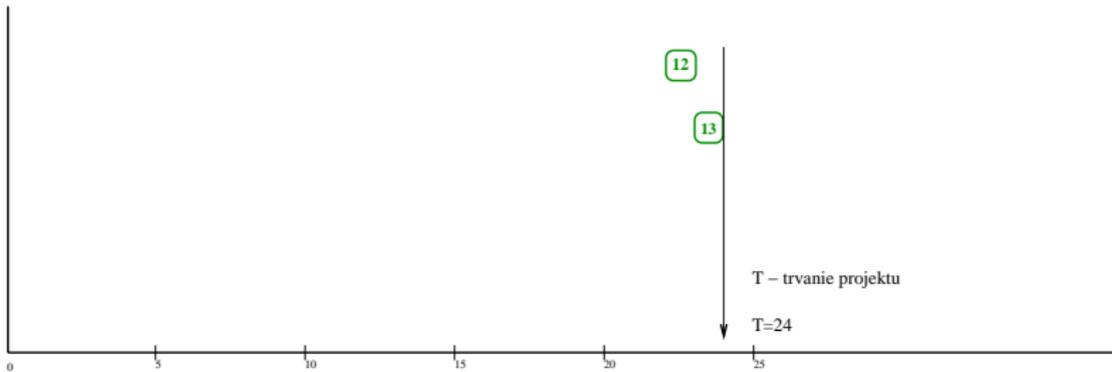
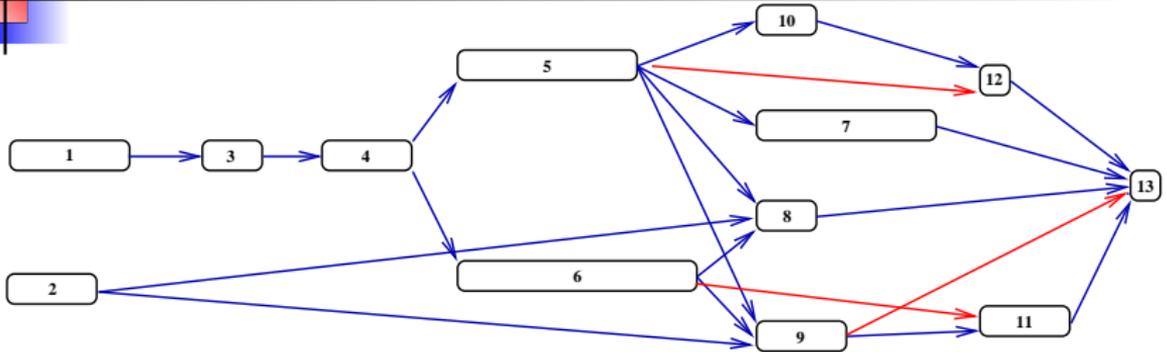
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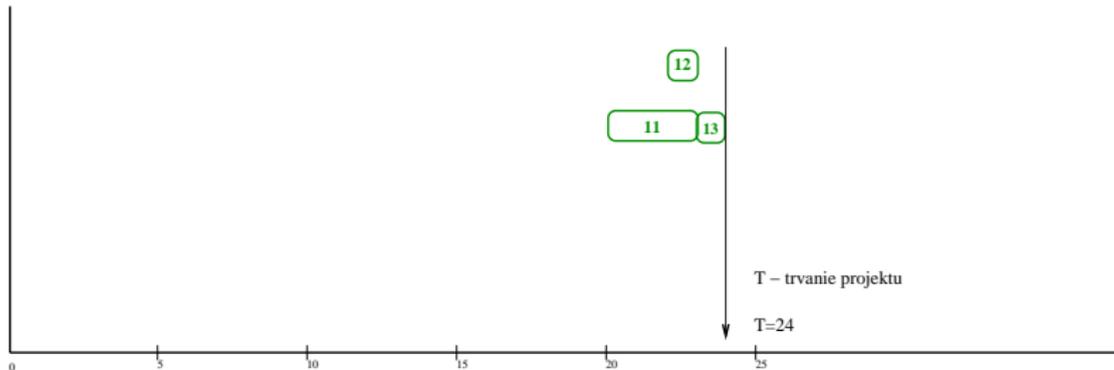
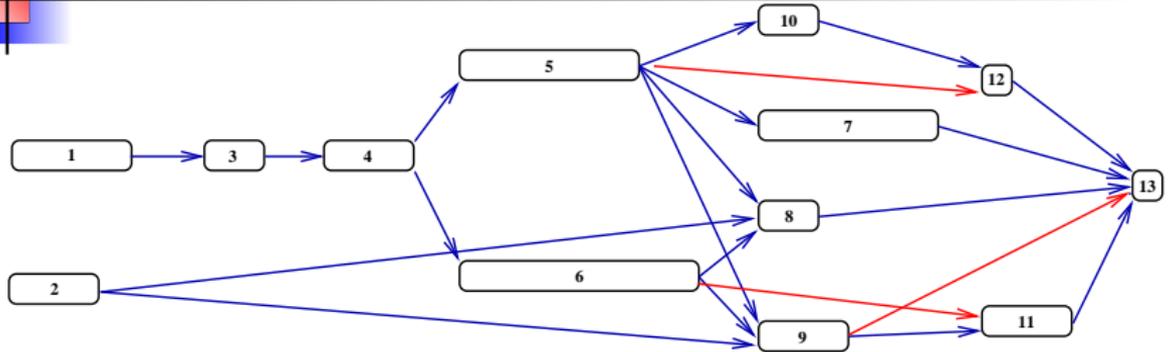
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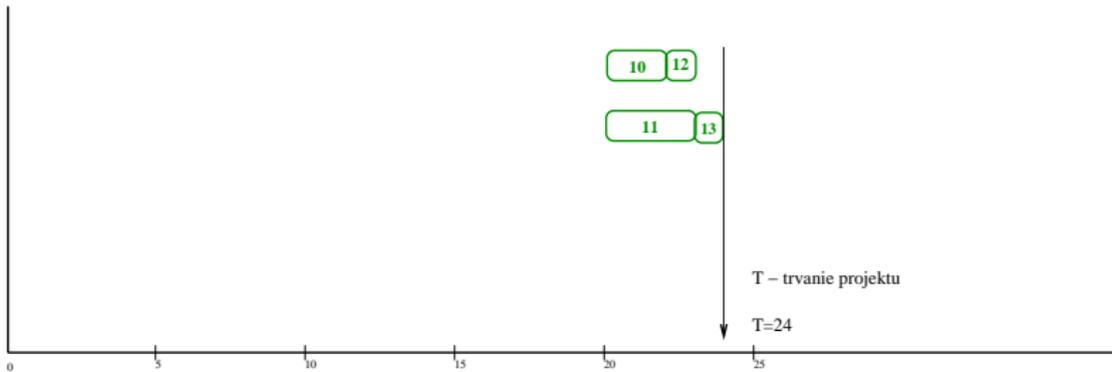
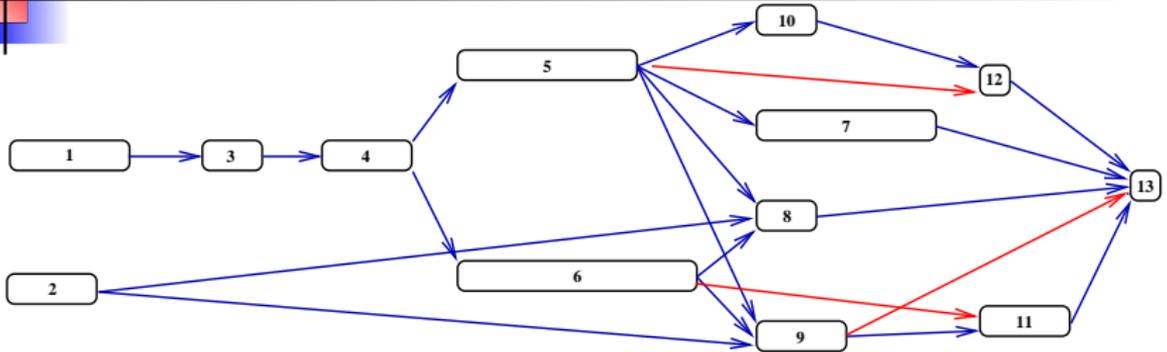
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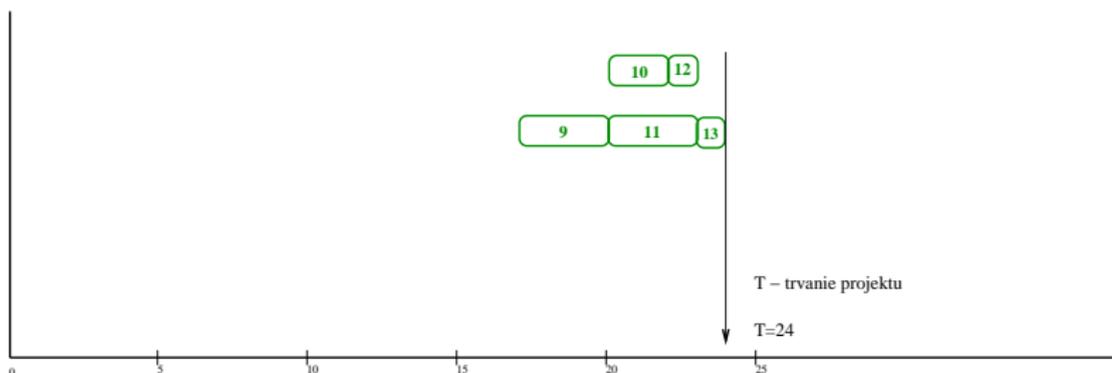
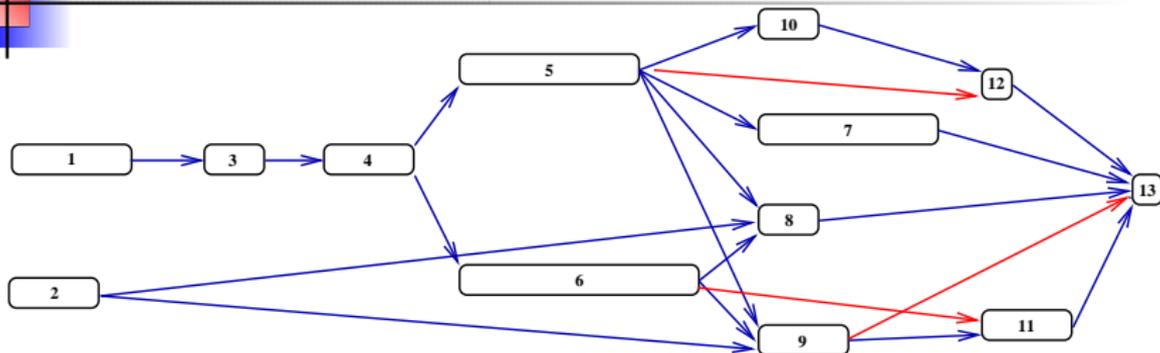
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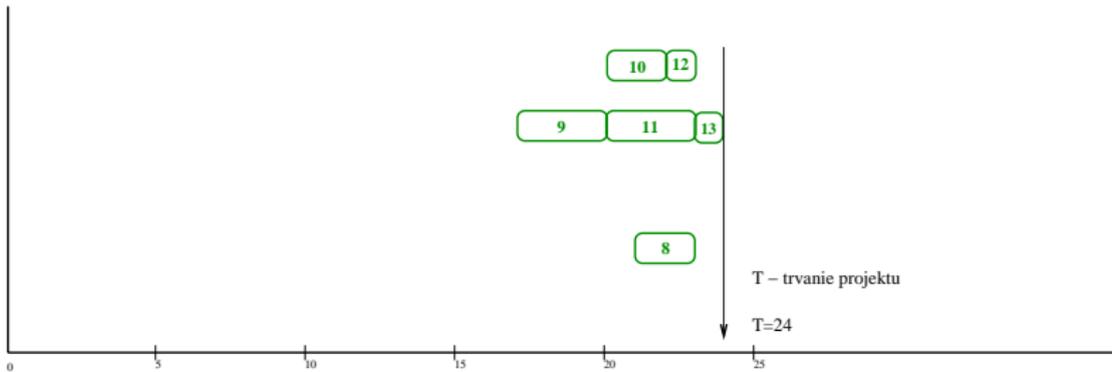
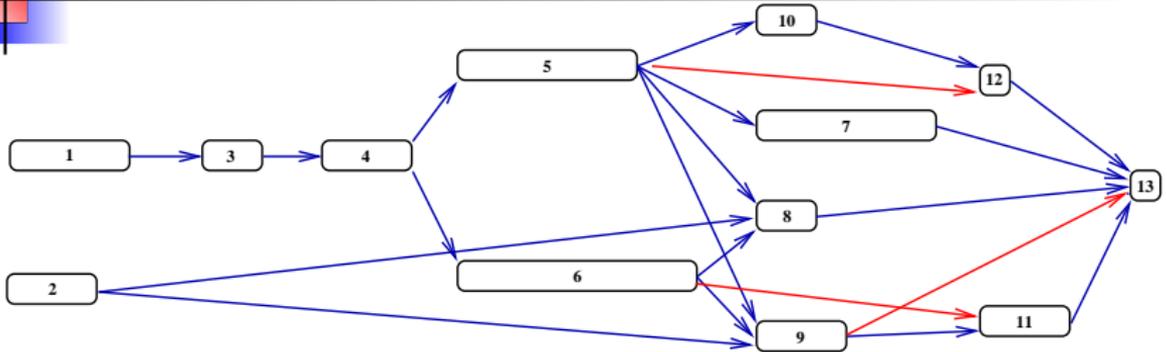
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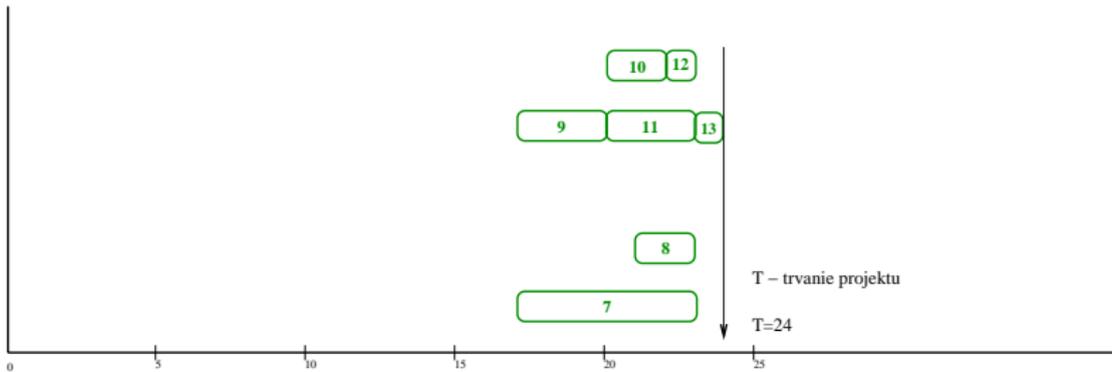
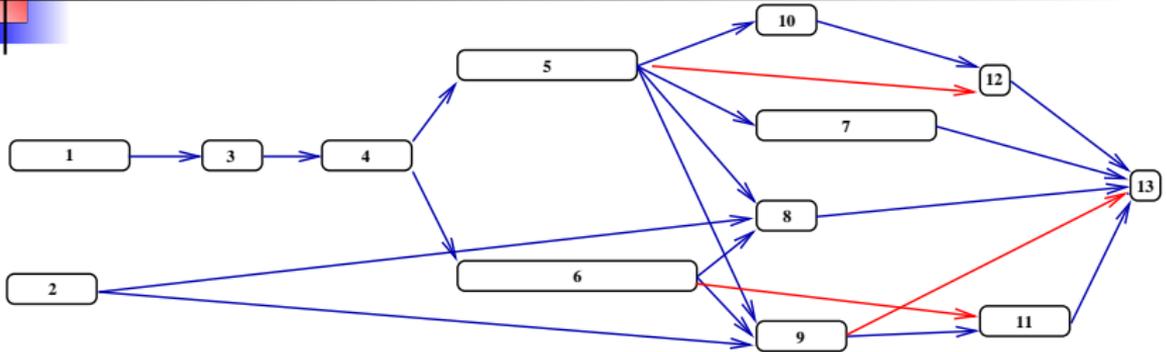
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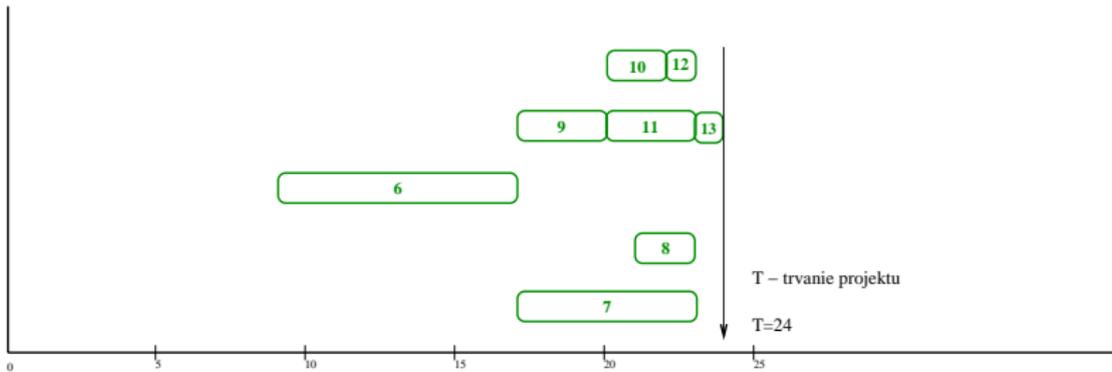
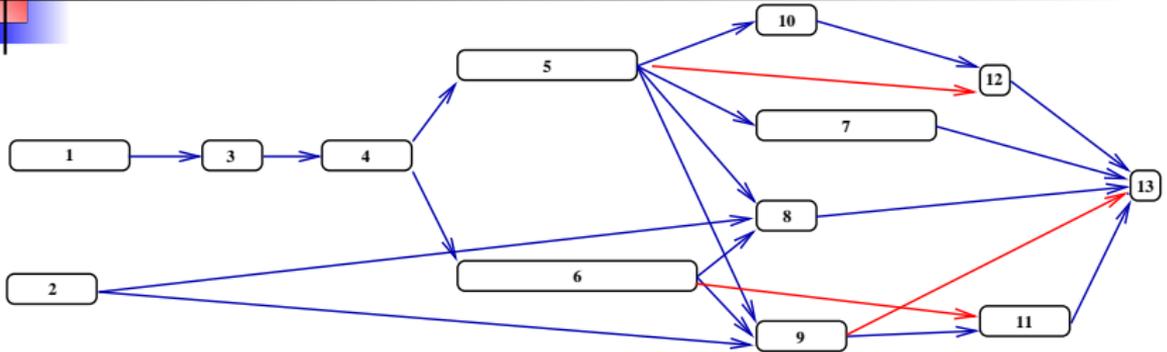
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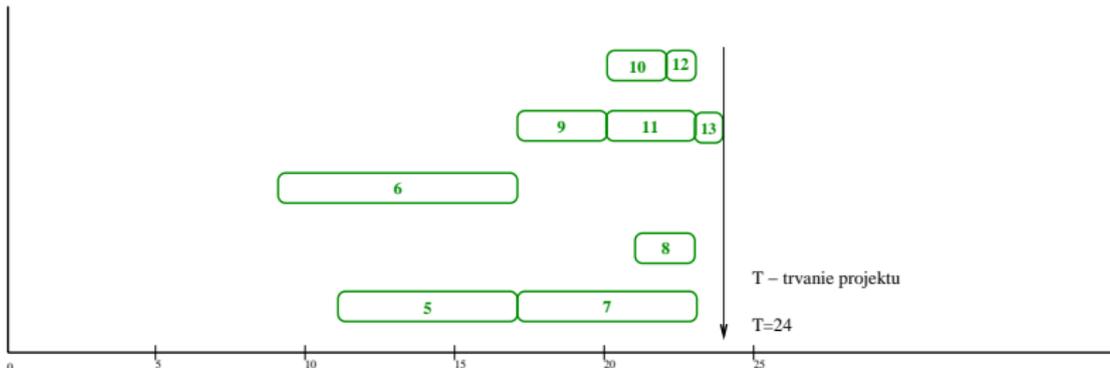
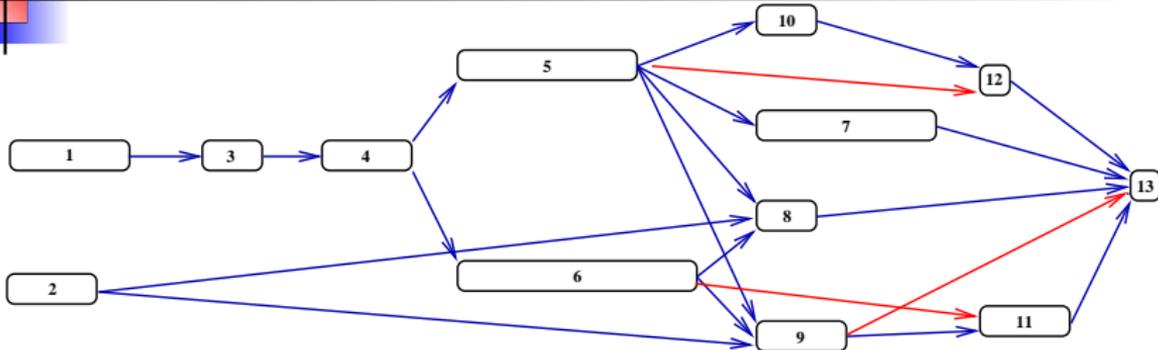
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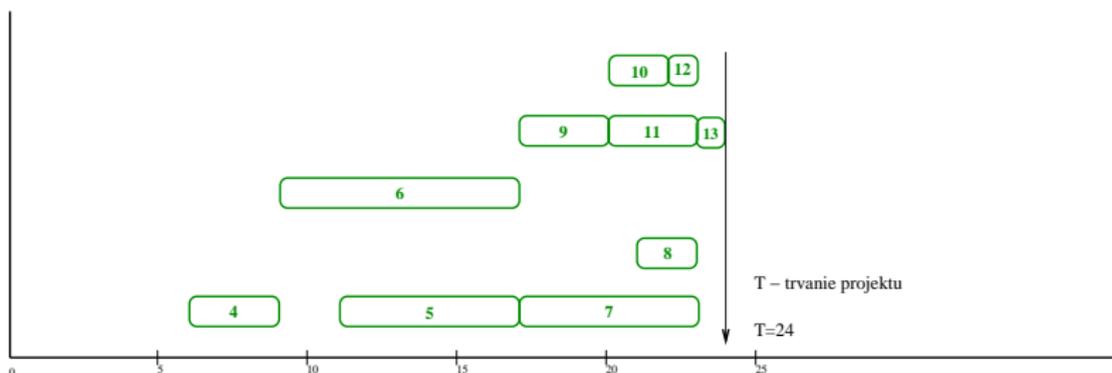
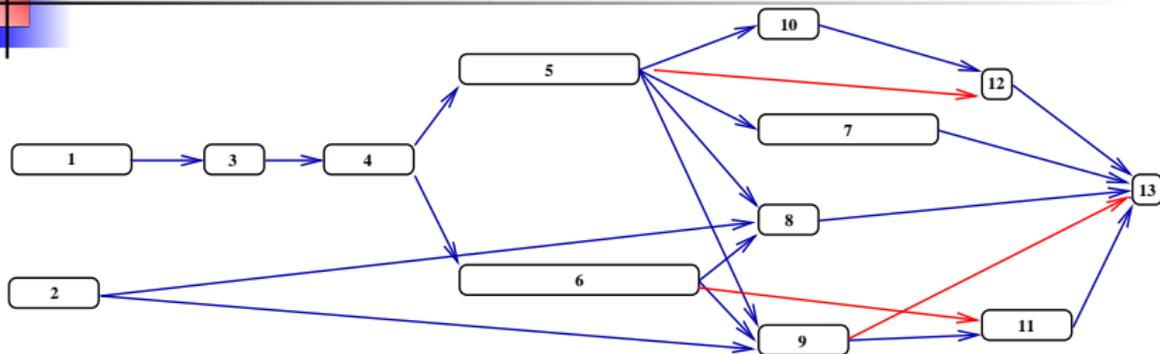
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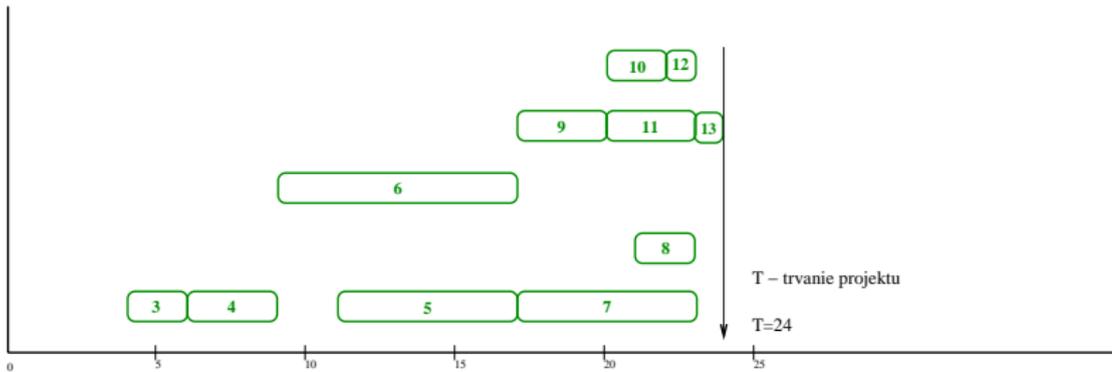
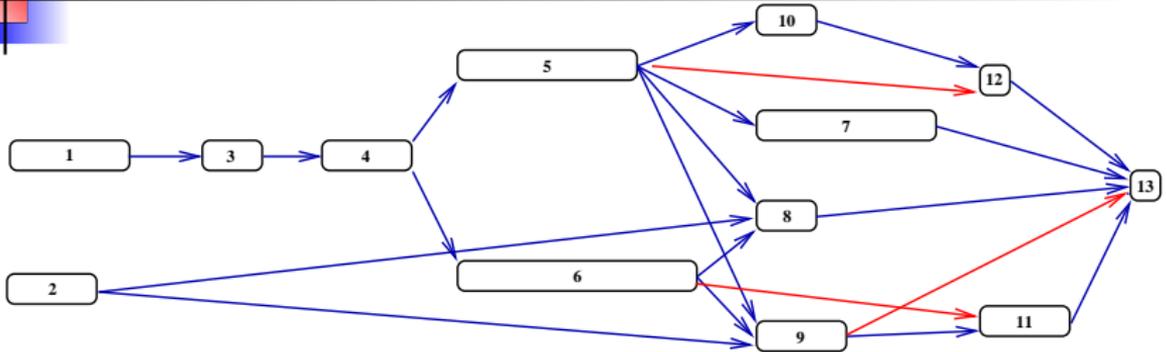
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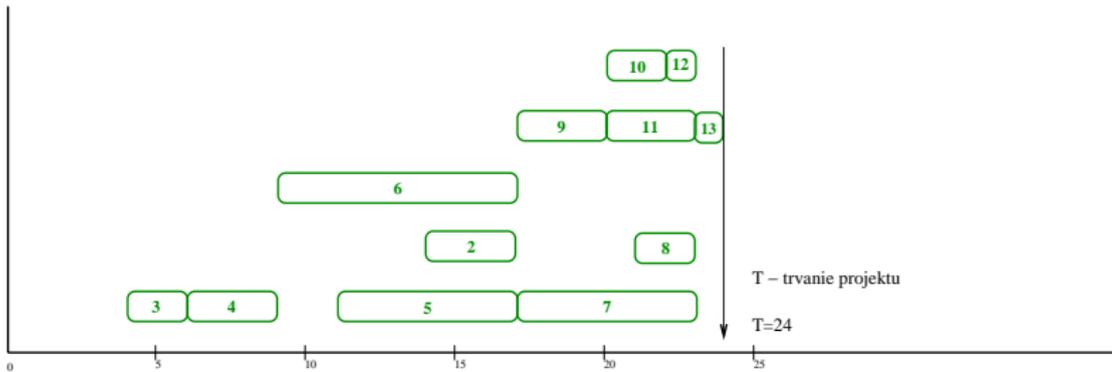
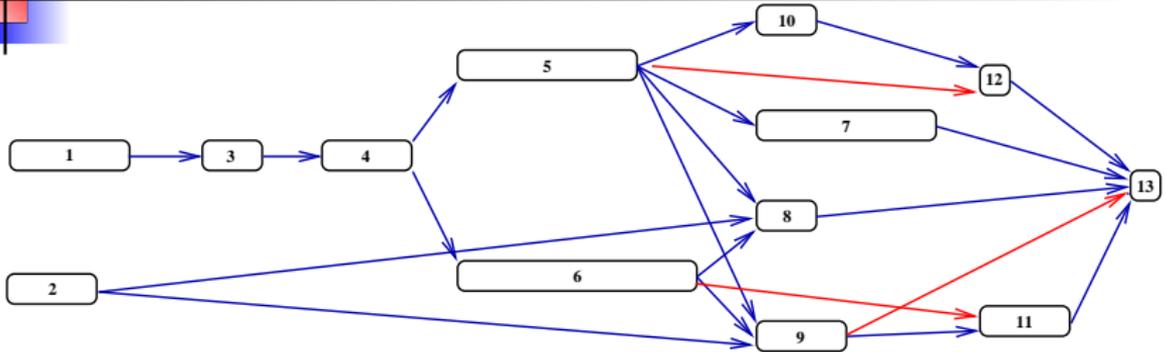
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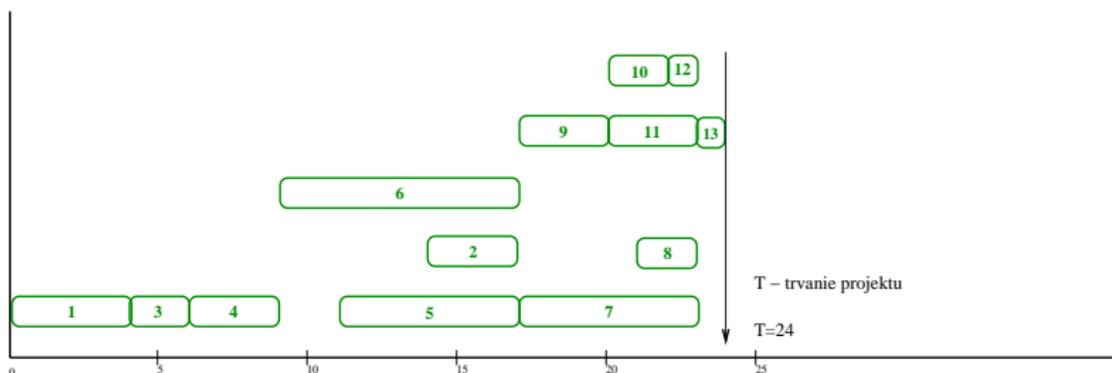
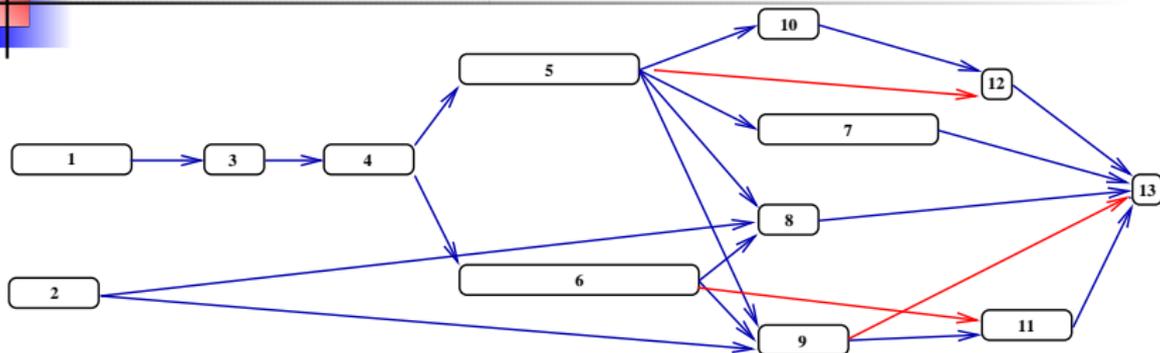
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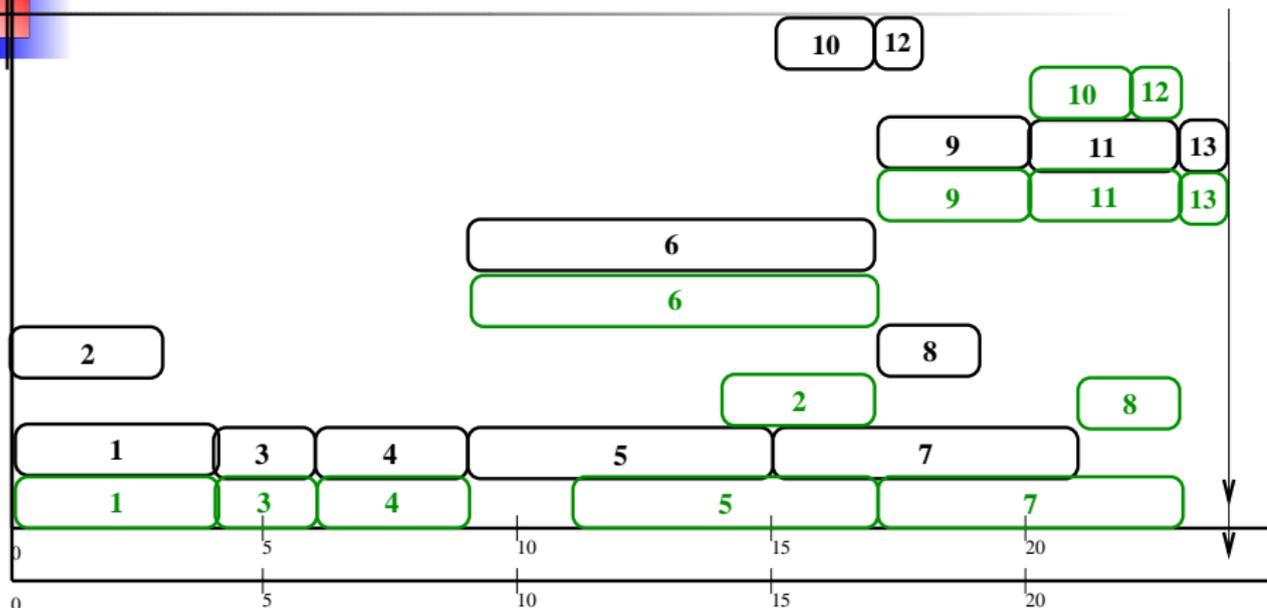
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## Comparison



Black – earliest possible positions of activities

Green – latest necessary positions of activities

### Algorithm

**Algorithm II.** to determine earliest beginnings  $z(v)$  of activities in digraph  $\vec{G} \leftarrow = (V, H, p)$ .

- **Step 1.** Create topological ordering  $v_1, v_2, \dots, v_n$  of vertex set of digraph  $\vec{G} \leftarrow$ .
- **Step 2.** Assign two labels  $z(v), x(v)$  to every vertex  $v \in V$ .  
Set  $x(v) := 0, z(v) := 0$  for every  $v \in V$ .
- **Step 3.** For  $k = 1, 2, \dots, n - 1$  do:  
For all vertices  $w \in V^+(v_k)$  do:  
If  $z(w) < z(v_k) + p(v_k)$ ,  
then  $z(w) := z(v_k) + p(v_k)$  and  $x(w) := v_k$ .
- **Step 4.** Compute the minimum completion time of project:  
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- **Step 3.** For  $k = 1, 2, \dots, n - 1$  do:  
For all vertices  $w \in V^+(v_k)$  do:  
If  $z(w) < z(v_k) + p(v_k)$ ,  
then  $z(w) := z(v_k) + p(v_k)$  and  $x(w) := v_k$ .
- **Step 4.** Compute the minimum completion time of project:  
$$T := \max\{z(w) + p(w) \mid w \in V, \text{odeg}(w) = 0\}$$



### Algorithm

**Algorithm II.** to determine latest necessary completion times  $k(v)$  of activities in digraph  $\vec{G} \leftarrow = (V, H, p)$ .

- **Step 1.** Create topological ordering  $v_1, v_2, \dots, v_n$  of vertex set of digraph  $\vec{G} \leftarrow$ .
- **Step 2.** Assign two labels  $k(v), y(v)$  to every vertex  $v \in V$ . Let  $T$  be the minimum completion time of the project. Set  $k(v) := T, y(v) := 0$  for every  $v \in V$ .
- **Step 3.** For  $i = n - 1, n - 2, \dots, 1$  do:  
For all vertices  $w \in V^+(v_i)$  do:  
If  $k(v_i) > k(w) - p(w)$ ,  
then  $k(v_i) := k(w) - p(w)$  and  $y(v_i) := w$ .



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## Computation of earliest possible starts

Forward stars			Table for computation of earliest possible starts of activities															
$v$	$p(v)$	$V^+(v)$	$v$	$p(v)$	$z(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13
						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0								3	3				
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
5	6	7 8 9 10 12	5	6	9							15	15	15	15		15	
6	8	8 9 11	6	8	9								17	17		17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17											19		
9	3	11 13	9	3	17											20		
10	2	12	10	2	15												17	
11	3	13	11	3	20													23
12	1	13	12	1	17													
13	1	-	13	1	23													

$$T = \max\{z(v) + p(v) \mid v \in V\} = 24.$$

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$v$	$p(v)$	$V^+(v)$	$v$	$p(v)$	$z(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13
						$z(i)$												
1	4	3	1	4	0	0	0	0	0	0	0	0	0	0	0	0	0	0
2	3	8 9	2	3	0		4						3	3				
3	2	4	3	2	4			6										
4	3	5 6	4	3	6				9	9								
5	6	7 8 9 10 12	5	6	9						15	15	15	15			15	
6	8	8 9 11	6	8	9							17	17			17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17											19		
9	3	11 13	9	3	17											20		
10	2	12	10	2	15												17	
11	3	13	11	3	20													23
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$v$	$p(v)$	$V^+(v)$	$v$	$p(v)$	$z(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13
						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0							3	3					
3	2	4	3	2	4			6										
4	3	5 6	4	3	6				9	9								
5	6	7 8 9 10 12	5	6	9						15	15	15	15			15	
6	8	8 9 11	6	8	9							17	17			17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17											19		
9	3	11 13	9	3	17											20		
10	2	12	10	2	15												17	
11	3	13	11	3	20													23
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						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0								3	3				
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
5	6	7 8 9 10 12	5	6	9							15	15	15	15		15	
6	8	8 9 11	6	8	9								17	17		17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17											19		
9	3	11 13	9	3	17											20		
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$v$	$p(v)$	$V^+(v)$	$v$	$p(v)$	$z(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13
						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0								3	3				
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
5	6	7 8 9 10 12	5	6	9							15	15	15	15		15	
6	8	8 9 11	6	8	9								17	17		17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17												19	
9	3	11 13	9	3	17												20	
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						$z(i)$														
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0		
1	4	3	1	4	0			4												
2	3	8 9	2	3	0							3	3							
3	2	4	3	2	4				6											
4	3	5 6	4	3	6					9	9									
5	6	7 8 9 10 12	5	6	9							15	15	15	15			15		
6	8	8 9 11	6	8	9								17	17				17		
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						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0								3	3				
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
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			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0							3	3					
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
5	6	7 8 9 10 12	5	6	9							15	15	15	15		15	
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						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0								3	3				
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
5	6	7 8 9 10 12	5	6	9							15	15	15	15		15	
6	8	8 9 11	6	8	9								17	17		17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17											19		
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1	4	3	1	4	0			4										
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3	2	4	3	2	4				6									
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						$z(i)$													
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0	
1	4	3	1	4	0			4											
2	3	8 9	2	3	0								3	3					
3	2	4	3	2	4				6										
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5	6	7 8 9 10 12	5	6	9							15	15	15	15			15	
6	8	8 9 11	6	8	9								17	17				17	
7	6	13	7	6	15														21
8	2	11 13	8	2	17														19
9	3	11 13	9	3	17														20
10	2	12	10	2	15														17
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$v$	$p(v)$	$V^+(v)$	$v$	$p(v)$	$z(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13
						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0								3	3				
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
5	6	7 8 9 10 12	5	6	9							15	15	15	15		15	
6	8	8 9 11	6	8	9								17	17		17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17											19		
9	3	11 13	9	3	17											20		
10	2	12	10	2	15												17	
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						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0								3	3				
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
5	6	7 8 9 10 12	5	6	9							15	15	15	15		15	
6	8	8 9 11	6	8	9								17	17		17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17											19		
9	3	11 13	9	3	17											20		
10	2	12	10	2	15												17	
11	3	13	11	3	20													23
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						$z(i)$												
			-		-	0	0	0	0	0	0	0	0	0	0	0	0	0
1	4	3	1	4	0			4										
2	3	8 9	2	3	0								3	3				
3	2	4	3	2	4				6									
4	3	5 6	4	3	6					9	9							
5	6	7 8 9 10 12	5	6	9							15	15	15	15		15	
6	8	8 9 11	6	8	9								17	17		17		
7	6	13	7	6	15													21
8	2	11 13	8	2	17											19		
9	3	11 13	9	3	17											20		
10	2	12	10	2	15												17	
11	3	13	11	3	20													23
12	1	13	12	1	17													
13	1	-	13	1	23													

$$T = \max\{z(v) + p(v) \mid v \in V\} = 24.$$

## Computation of latest necessary completion times

Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24														24
12	13	12	1	22	23														23
11	13	11	3	20	23														23
10	12	10	2	20	22														22
9	11 13	9	3	17	20														20
8	11 13	8	2	18	20														20
7	13	7	6	17	23														23
6	8 9 11	6	8	9	17														17
5	7 8 9 10 12	5	6	11	17														17
4	5 6	4	3	6	9														9
3	4	3	2	4	6														6
2	8 9	2	3	14	17														17
1	3	1	4	0	4														4

## Computation of latest necessary completion times

Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
13	-	13	1	23	24	24	24	24	24	24	24	24	24	24	24	24	24	24	24
12	13	12	1	22	23												23		
11	13	11	3	20	23											23			
10	12	10	2	20	22										22				
9	11 13	9	3	17	20									20					
8	11 13	8	2	18	20								20						
7	13	7	6	17	23							23							
6	8 9 11	6	8	9	17						17								
5	7 8 9 10 12	5	6	11	17					17									
4	5 6	4	3	6	9				9										
3	4	3	2	4	6			6											
2	8 9	2	3	14	17		17												
1	3	1	4	0	4	4													

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$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
13	-	13	1	23	24	24	24	24	24	24	24	24	24	24	24	24	24	24	24
12	13	12	1	22	23												23		
11	13	11	3	20	23												23		
10	12	10	2	20	22												22		
9	11 13	9	3	17	20												20		
8	11 13	8	2	18	20												20		
7	13	7	6	17	23												23		
6	8 9 11	6	8	9	17												17		
5	7 8 9 10 12	5	6	11	17												17		
4	5 6	4	3	6	9												9		
3	4	3	2	4	6												6		
2	8 9	2	3	14	17												17		
1	3	1	4	0	4	4													

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$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24												24	24	
12	13	12	1	22	23												23	24	
11	13	11	3	20	23											23			
10	12	10	2	20	22										22				
9	11 13	9	3	17	20									20					
8	11 13	8	2	18	20									20					
7	13	7	6	17	23									23					
6	8 9 11	6	8	9	17									17					
5	7 8 9 10 12	5	6	11	17									17					
4	5 6	4	3	6	9				9										
3	4	3	2	4	6			6											
2	8 9	2	3	14	17		17												
1	3	1	4	0	4	4													

## Computation of latest necessary completion times

Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24														24
12	13	12	1	22	23														23
11	13	11	3	20	23														23
10	12	10	2	20	22														22
9	11 13	9	3	17	20														20
8	11 13	8	2	18	20														20
7	13	7	6	17	23														23
6	8 9 11	6	8	9	17														17
5	7 8 9 10 12	5	6	11	17														17
4	5 6	4	3	6	9														9
3	4	3	2	4	6														6
2	8 9	2	3	14	17														17
1	3	1	4	0	4														4

## Computation of latest necessary completion times

Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24														24
12	13	12	1	22	23														23
11	13	11	3	20	23														23
10	12	10	2	20	22														22
9	11 13	9	3	17	20														20
8	11 13	8	2	18	20														20
7	13	7	6	17	23														23
6	8 9 11	6	8	9	17														17
5	7 8 9 10 12	5	6	11	17														17
4	5 6	4	3	6	9														9
3	4	3	2	4	6														6
2	8 9	2	3	14	17														17
1	3	1	4	0	4														4

## Computation of latest necessary completion times

Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24												24	24	
12	13	12	1	22	23												23		
11	13	11	3	20	23											23			
10	12	10	2	20	22										22				
9	11 13	9	3	17	20									20					
8	11 13	8	2	18	20									20					
7	13	7	6	17	23									23					
6	8 9 11	6	8	9	17									17					
5	7 8 9 10 12	5	6	11	17									17					
4	5 6	4	3	6	9									9					
3	4	3	2	4	6									6					
2	8 9	2	3	14	17									17					
1	3	1	4	0	4	4													

# Computation of latest necessary completion times

Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24												24	24	
12	13	12	1	22	23												23	24	
11	13	11	3	20	23											23			
10	12	10	2	20	22										22				
9	11 13	9	3	17	20									20					
8	11 13	8	2	18	20									20					
7	13	7	6	17	23									23					
6	8 9 11	6	8	9	17									17					
5	7 8 9 10 12	5	6	11	17									17					
4	5 6	4	3	6	9									9					
3	4	3	2	4	6									6					
2	8 9	2	3	14	17									17					
1	3	1	4	0	4	4													





## Computation of latest necessary completion times

Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24														24
12	13	12	1	22	23														23
11	13	11	3	20	23														23
10	12	10	2	20	22														22
9	11 13	9	3	17	20														20
8	11 13	8	2	18	20														20
7	13	7	6	17	23														23
6	8 9 11	6	8	9	17														17
5	7 8 9 10 12	5	6	11	17														17
4	5 6	4	3	6	9														9
3	4	3	2	4	6														6
2	8 9	2	3	14	17														17
1	3	1	4	0	4														4

## Computation of latest necessary completion times

Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24														24
12	13	12	1	22	23														23
11	13	11	3	20	23														23
10	12	10	2	20	22														22
9	11 13	9	3	17	20														20
8	11 13	8	2	18	20														20
7	13	7	6	17	23														23
6	8 9 11	6	8	9	17														17
5	7 8 9 10 12	5	6	11	17														17
4	5 6	4	3	6	9														9
3	4	3	2	4	6														6
2	8 9	2	3	14	17														17
1	3	1	4	0	4														4

## Computation of latest necessary completion times

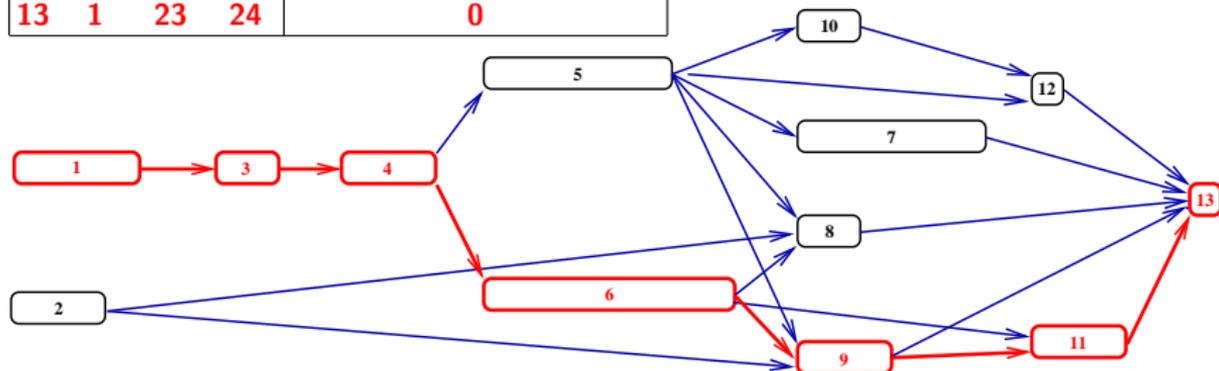
Forward stars Table for computation of latest necessary completion times of activities

$v$	$V^+(v)$	$v$	$p(v)$	$k(v) - p(v)$	$k(v)$	1	2	3	4	5	6	7	8	9	10	11	12	13	
						$k(v) = \min\{k(i) - p(i) \mid i \in V^+(v)\}$													
		-		-	-	24	24	24	24	24	24	24	24	24	24	24	24	24	24
13	-	13	1	23	24														24
12	13	12	1	22	23														23
11	13	11	3	20	23														23
10	12	10	2	20	22														22
9	11 13	9	3	17	20														20
8	11 13	8	2	18	20														20
7	13	7	6	17	23														23
6	8 9 11	6	8	9	17														17
5	7 8 9 10 12	5	6	11	17														17
4	5 6	4	3	6	9														9
3	4	3	2	4	6														6
2	8 9	2	3	14	17														17
1	3	1	4	0	4	4													



## Critical activities, critical path

$v$	$p(v)$	$z(v)$	$k(v)$	$R(v) = k(v) - z(v) - p(v)$
1	4	0	4	0
2	3	0	17	14
3	2	4	6	0
4	3	6	9	0
5	6	9	17	2
6	8	9	17	0
7	6	15	23	2
8	2	17	20	1
9	3	17	20	0
10	2	15	22	3
11	3	20	23	0
12	1	17	23	5
13	1	23	24	0





## Classical interpretation of CPM method

Let  $\mathcal{U}$  be a project planning problem given by an activity set  $\mathcal{A}$ , precedence relation  $\prec$  on the set  $\mathcal{A}$  and by a real function  $c : \mathcal{A} \rightarrow \mathbb{R}$  assigning to every activity  $A \in \mathcal{A}$  its processing time  $p(A)$ .

**AOA (activity on arc) network** is a weakly connected acyclic edge weighted digraph  $\vec{G} = (V, H, p)$  containing exactly one vertex  $s$  – start of the project and exactly one vertex  $f$  – finish of the project with following properties:

Every vertex  $v$  of  $V$  is reachable from the start  $s$  and the finish  $f$  is reachable from every vertex  $v$  of  $V$ .

Arcs of AOA network represent activities – for every activity  $A \in \mathcal{A}$  is assigned exactly one arc having arc weight equal to processing time  $p(A)$  of  $A$ .

Vertices represent events of beginnings and completions of activities. If  $A \prec B$  – i.e. activity  $A$  immediately precedes activity  $B$  then the arc  $B$  has its head identical with the tail of the arc  $A$ .





## Classical interpretation of CPM method

Denote by  $d_{\max}(x, y)$  the length of the longest  $x$ - $y$  directed path in AOA network  $\vec{G}$ . Remember that vertex 1 is the start and vertex  $n$  is the finish of corresponding project.

The earliest possible time  $T_i$  of activities outgoing from every vertex  $i \in V$  is calculated as

$$T_i = d_{\max}(1, i)$$

The latest possible completion time  $T'_i$  of activities incomming into vertex  $i \in V$  is calculated as

$$T'_i = T_n - d_{\max}(i, n)$$

The minimum completion time  $T$  of the project is

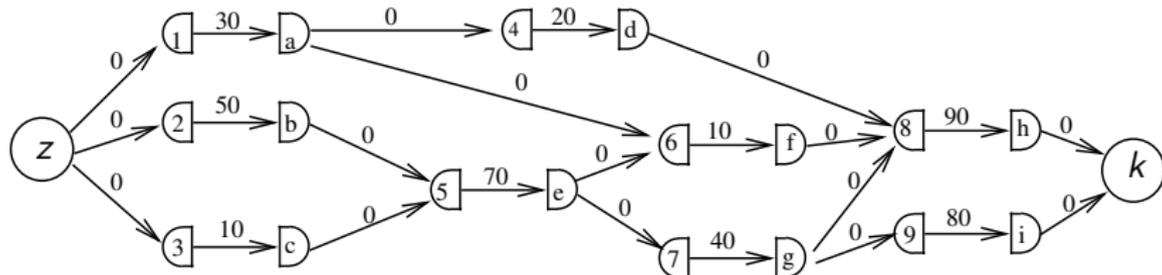
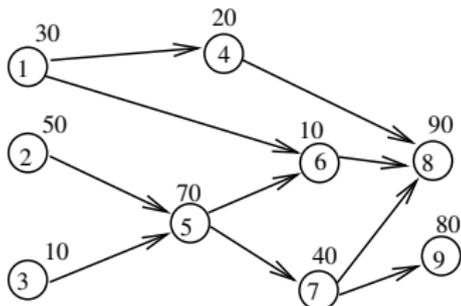
$$T = T_n.$$

Every directed 1 -  $n$  path having the length equal to  $T$  is called a **critical path**. (There can exist mor ctritical paths).

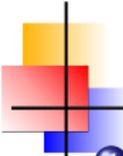
Activities belonging to a critical path are called **critical activities**.

**Time reserve**  $R_i$  in a vertex  $i$  is  $R_i = T'_i - T_i$ .

# Construction of AOA network



Construction of AOA network  $\vec{G}_S$  (below) from precedence digraph  $\vec{G}$  (above).



## Construction of AOA network

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- 1 Create digraph of immediate precedence  $\vec{G}_{\leftarrow}$ .
- 2 Declare all arcs of  $\vec{G}_{\leftarrow}$  as dummy arcs with processing times equal to 0.
- 3 Add two vertices  $z$  and  $k$ .
- 4 Add arcs of the type  $(z, v)$  for all vertices  $v$  such that  $\text{iddeg}(v) = 0$ . Consider these arcs as dummy arcs with processing times equal to 0.
- 5 Add arcs of the type  $(v, k)$  for all vertices  $v$  such that  $\text{odeg}(v) = 0$ . These arcs consider as dummy arcs with processing times equal to 0.
- 6 Split every vertex representing an activity into input and output part. Add an arc with head equal to input part and tail equal to output part of every splitted vertex and set weight of this arc equal to processing time of corresponding activity.